

Issue: 02

Date: 2023/06/02

**Document Title:**

Gama RTk5 End User Manual

**Summary / Scope:**

This document is meant to support Carlson End Users as a single go-to document to guide and answer any questions on how to use Gama in combination with the RTk5 tablet. For guidance on how to use the RTk5 tablet in general or SurvPC please consult dedicated manuals.

**Reason for Issue:**

- Support End Users getting started with Gama and RTk5 product;
- Single go-to document for all questions on how to use Gama with the RTk5.

**Distribution:**

Suitable for external distribution.

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## 1 Gama RTK Technology

The Gama RTK Engine (named after famous explorer Vasco da Gama) is Carlson Software's next generation RTK engine.

Gama deploys a range of new technologies to deliver best-in-class performance.

See our [Gama RTK White Paper](#) for details on RTK technology and competitive test results.

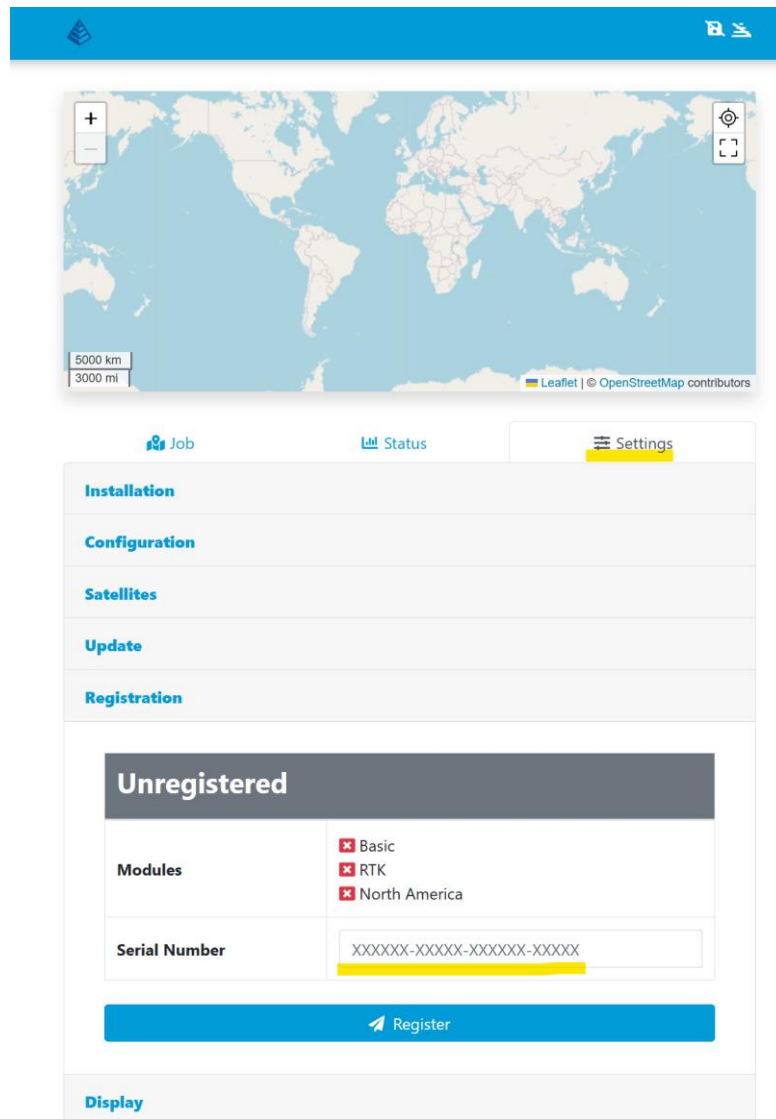
## 2 Gama RTK Engine Registration

Before using Gama you must register with a valid license key.

Step 1) – Double-click Gama GNSS-UI logo on the Windows Desktop.

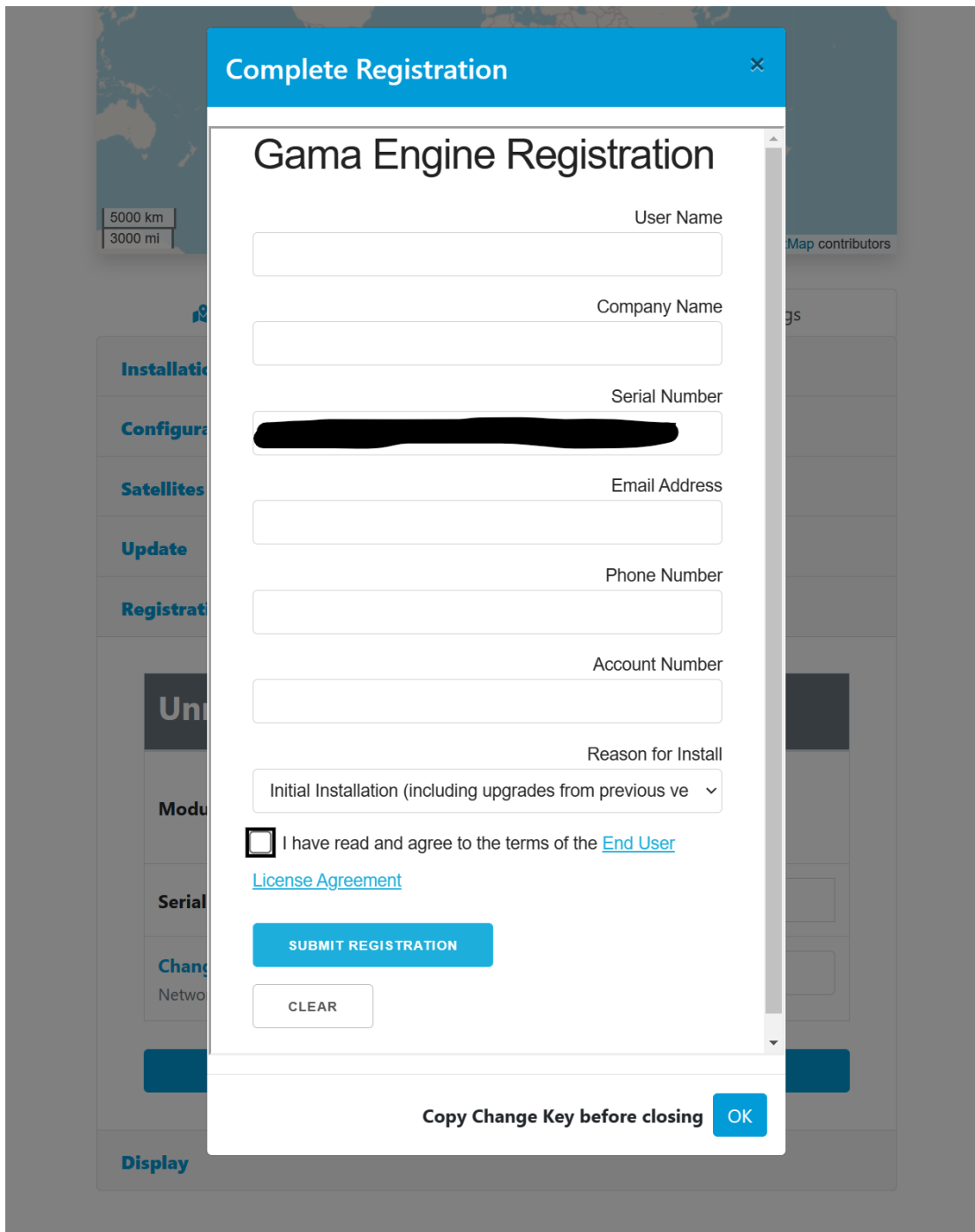


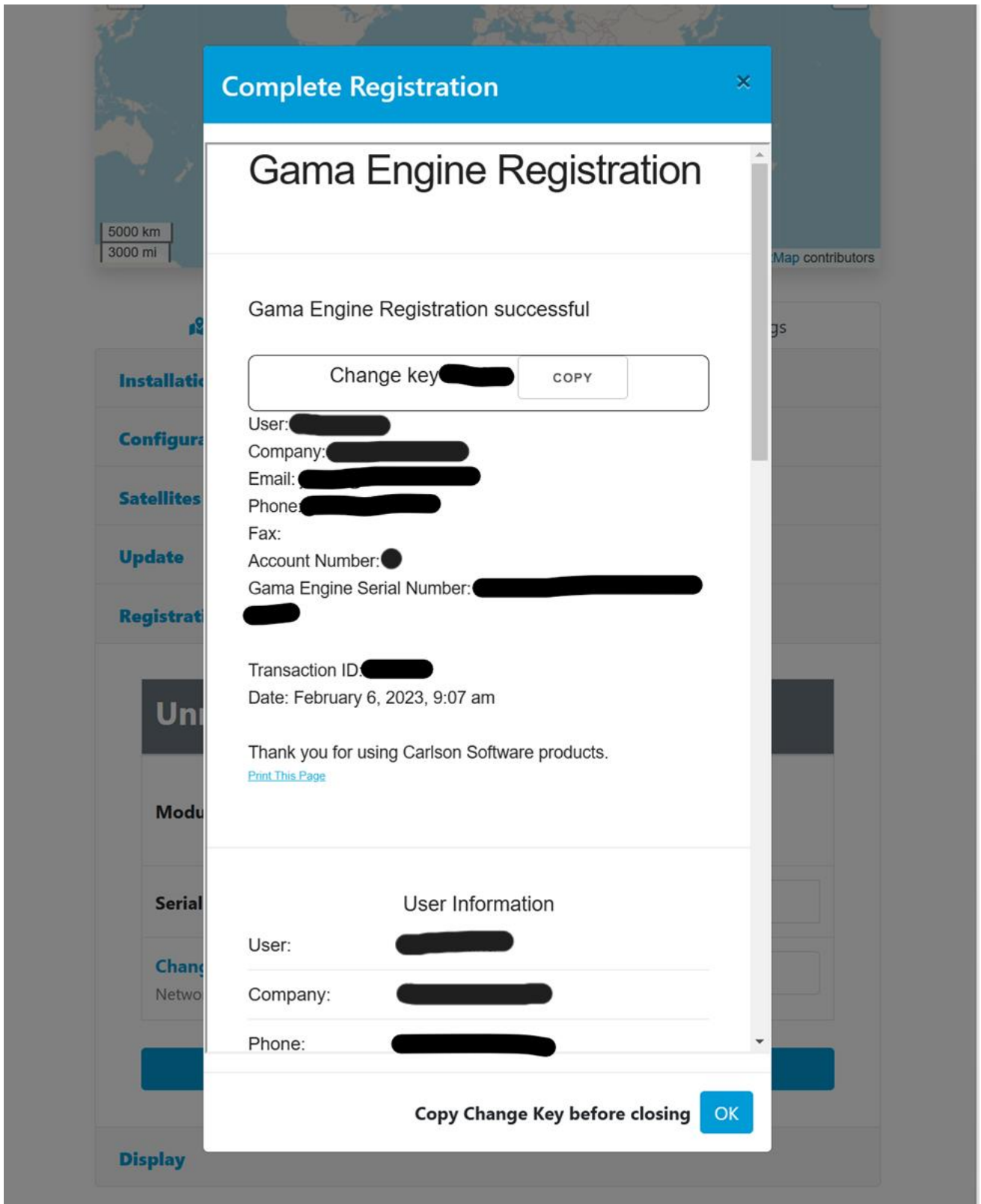
Step 2) – Click Settings tab and scroll down to “Registration”.



Step 3) – Ensure the device has internet access, type in the Gama RTk5 serial number and click “Register”. If you don’t have a serial number please request one from your Carlson Software point of contact.

Step 4) – Type in personal details to complete registration and retrieve Change Key – You will need to copy the Change Key from this page, it is not automatic:







Step 5) – Apply Change Key to complete registration. You should see the Web UI show “Registered” status and blue check boxes on the multiple modules.

**Registration**

## Registered

<b>Modules</b>	<input checked="" type="checkbox"/> Basic <input checked="" type="checkbox"/> RTK <input checked="" type="checkbox"/> North America
<b>Serial Number</b>	

 Unregister

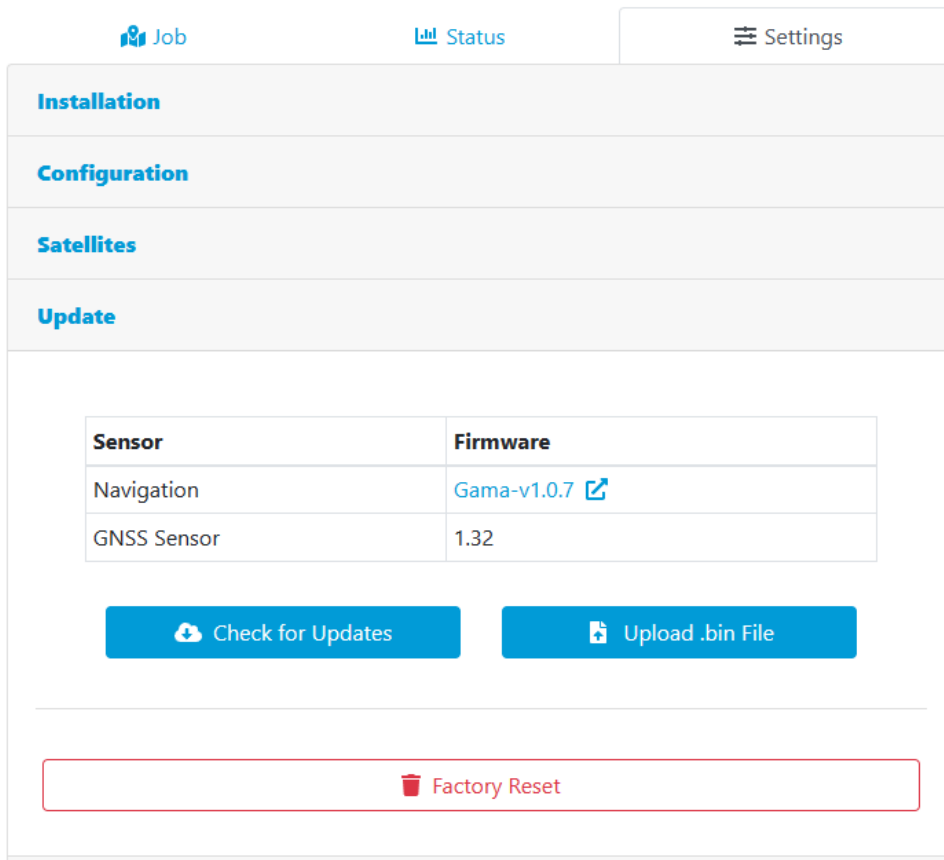
**Display**

### 3 Updating Gama

Gama can be updated either via the WebUI with an internet connected device, or via a downloaded bin file from the Carlson website.

The preferred method is to allow the WebUI to update itself via the “[Check for Updates](#)” button.

Alternatively, *special circumstances* may require usage of the “[Upload .bin File](#)” using an update bin.





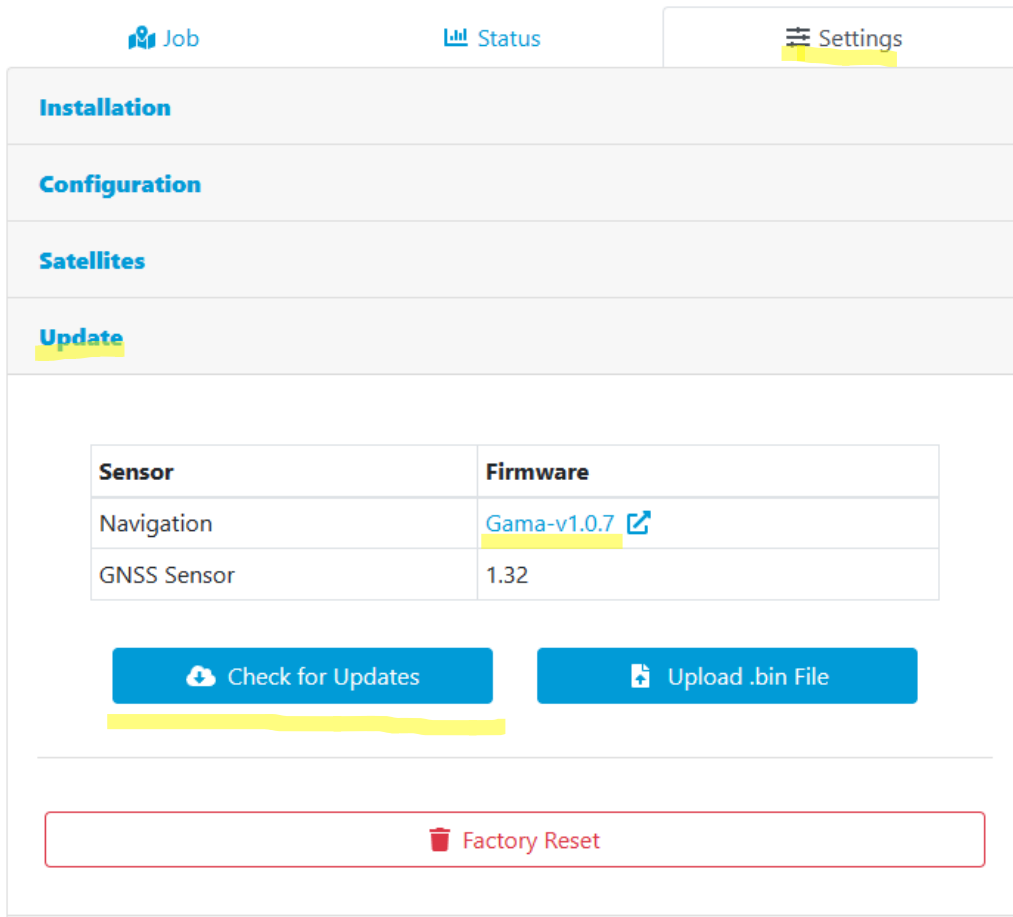
### 3.1 Updating Gama via Check for Updates

Step 1) – Ensure the RTk5 is connected to the Internet.


Step 2) – Open Gama Web UI using the Desktop icon (alternatively open a browser on the RTk5 tablet and type in 127.0.0.1).



Step 3) – Click Settings tab and scroll down to “Update”.



The screenshot shows the GAMA Settings page with the 'Settings' tab selected. The 'Update' section is highlighted, containing a table with sensor and firmware information, and buttons for 'Check for Updates' and 'Upload .bin File'.

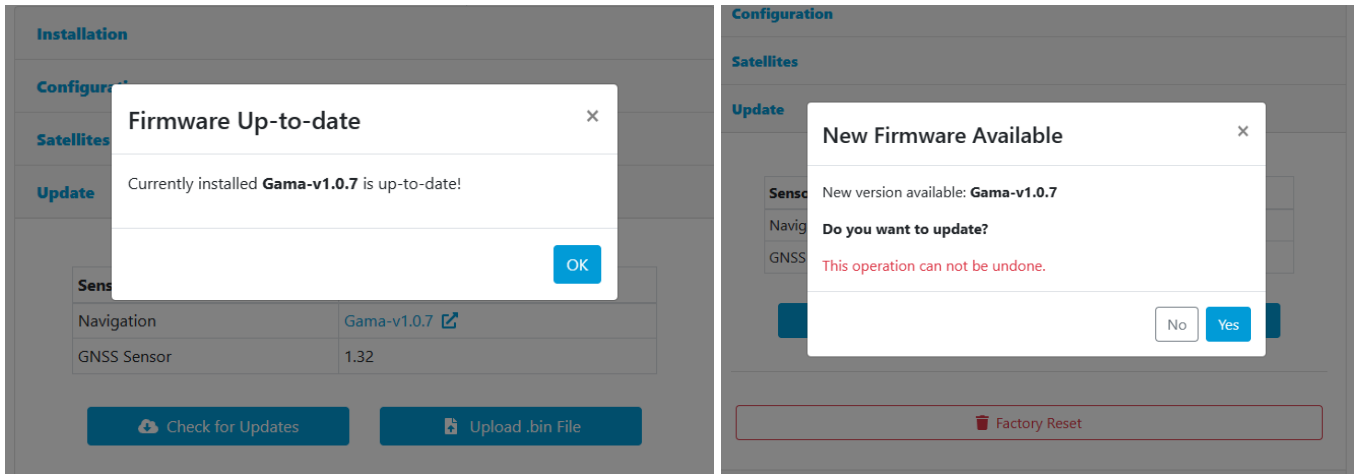
Sensor	Firmware
Navigation	<a href="#">Gama-v1.0.7</a> 
GNSS Sensor	1.32

**Check for Updates**      **Upload .bin File**

**Factory Reset**

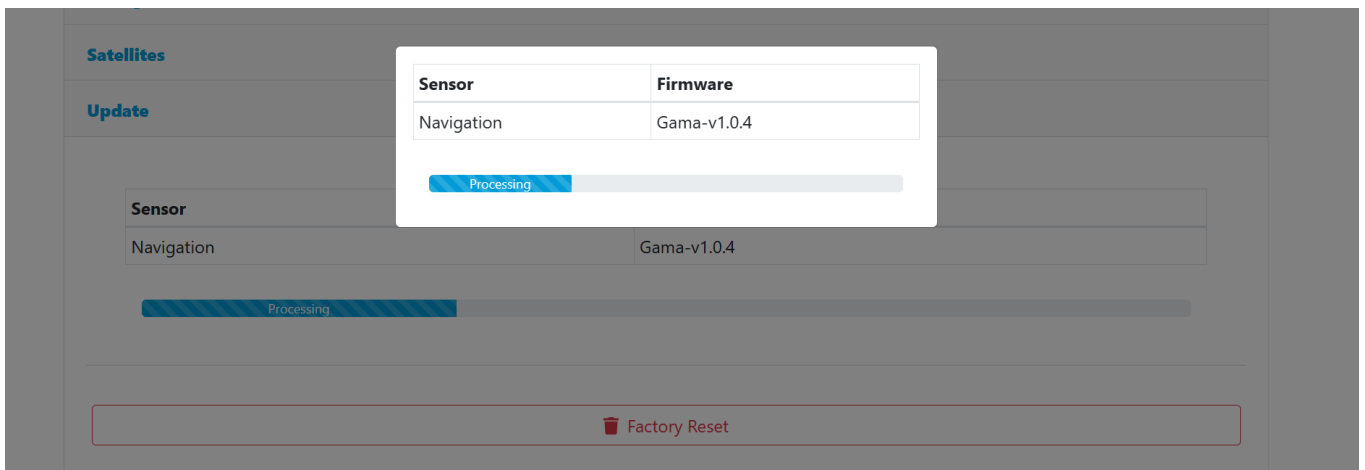
Step 4) – Click “Check for Updates”.

Step 5) – The resulting dialog will either display the current firmware is up-to-date, or if there’s a new update.



Step 6) – To proceed with the update, select “Yes.”

Step 7) – Wait until update procedure finishes.



Step 8) – Once update finishes it will automatically restart and the Web UI will show up again with the new firmware version. You can then use Gama normally via the Web UI or with SurvPC.

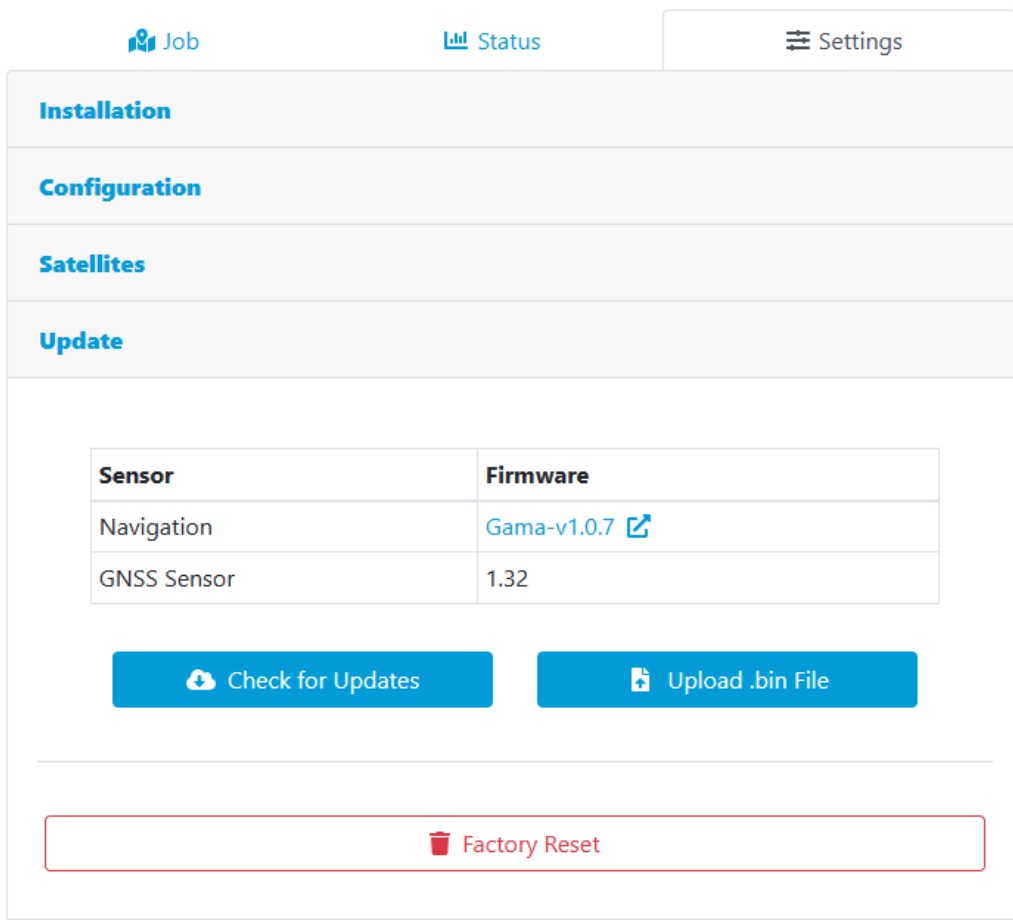
### 3.2 Updating Gama via Manually Downloaded Bin File

Step 1) – Request Gama update .bin file from your Carlson Software point of contact.

Step 2) – Open Gama Web UI using the Desktop icon (alternatively open a browser on the RTk5 tablet and type in 127.0.0.1).

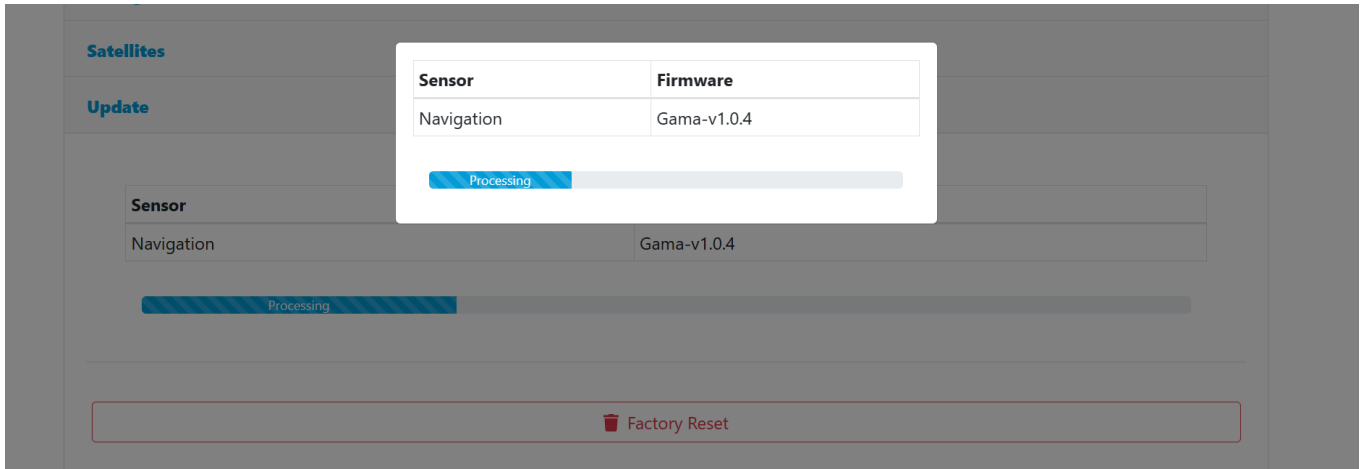


Step 3) – Click Settings tab and scroll down to “Update”.



Step 4) – Click “Upload” button on the Web UI and select the update file.

Step 5) – Wait until update procedure finishes.



Step 6) – Once update finishes it will automatically restart and the Web UI will show up again with the new firmware version. You can then use Gama normally with SurvPC or via the Web UI.

## 4 Using Gama with SurvPC

Always make sure you have the latest version of SurvPC 7.

To connect SurvPC to Gama follow these steps:

Step 1) – Ensure you have the GNSS antenna correctly connected to the RTk5.

The GNSS antenna connector is the left SMA connector on top of the device:



RTk5 ships with Tallysman 3972XF and Harxon CHX-602A.



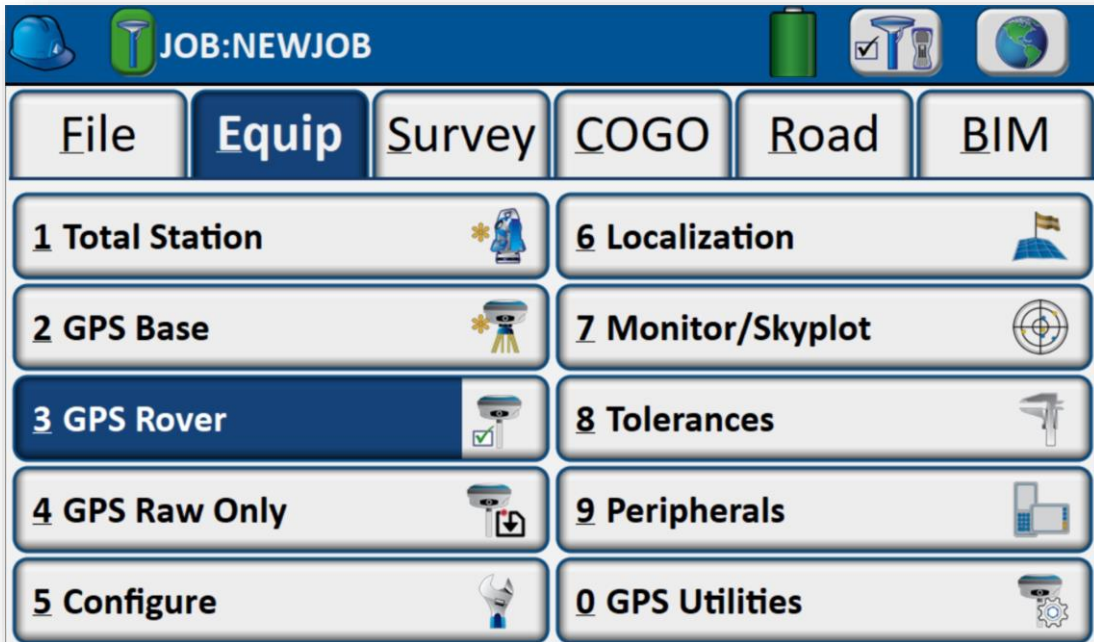
Tallysman TWI3972XF



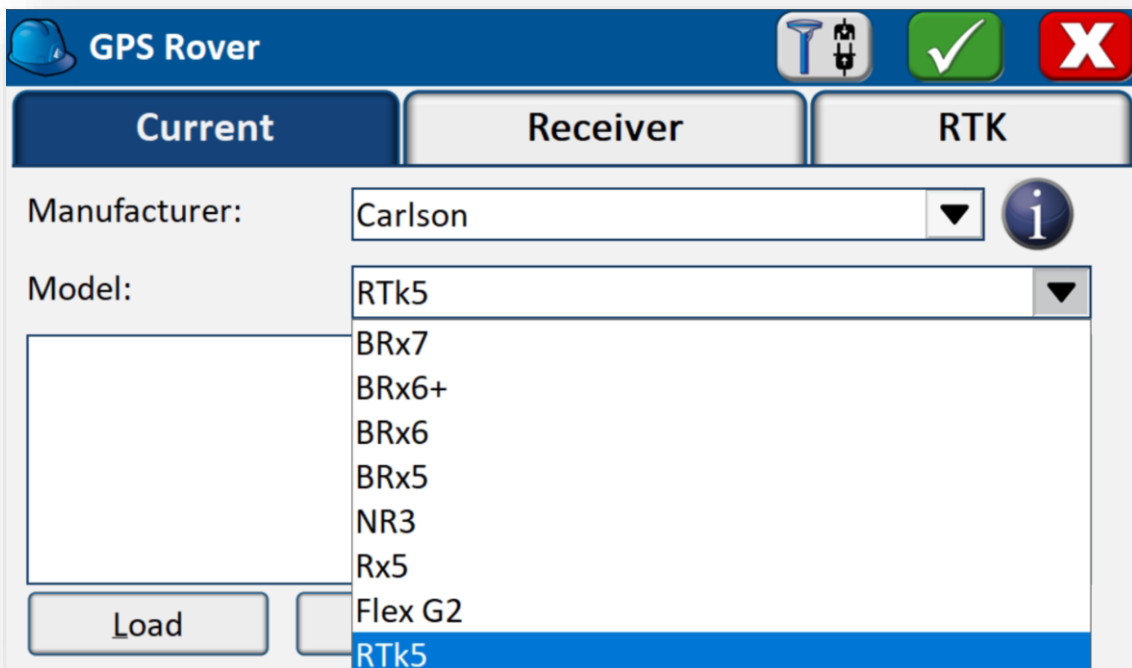
Harxon HXC\_CHX602A

Step 2) – Open SurvPC 7.

Step 3) – Click “Equipment” on the top menu and then click “3 GPS Rover”.

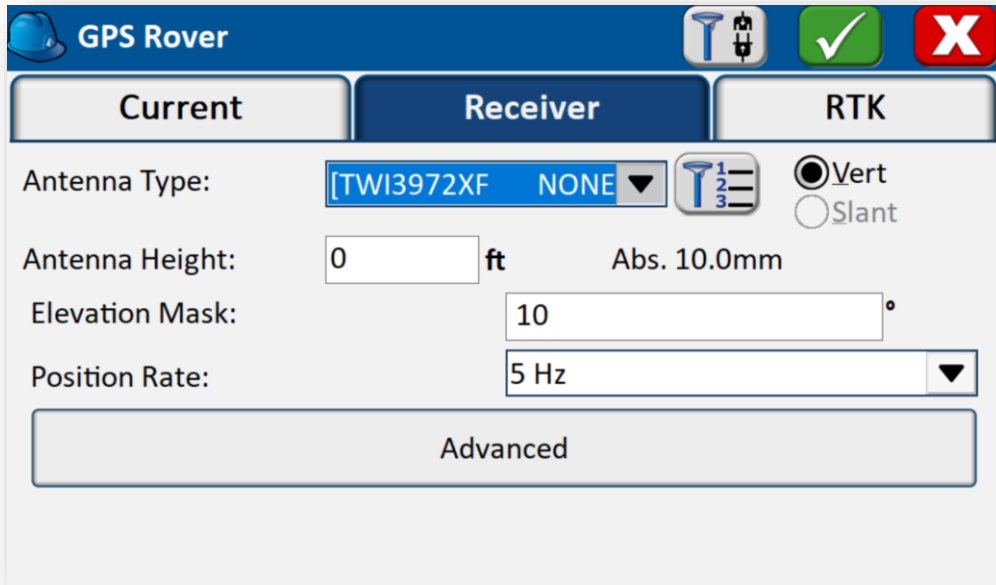


Step 4) – Under manufacturer select “Carlson” and pick “RTk5” under model.

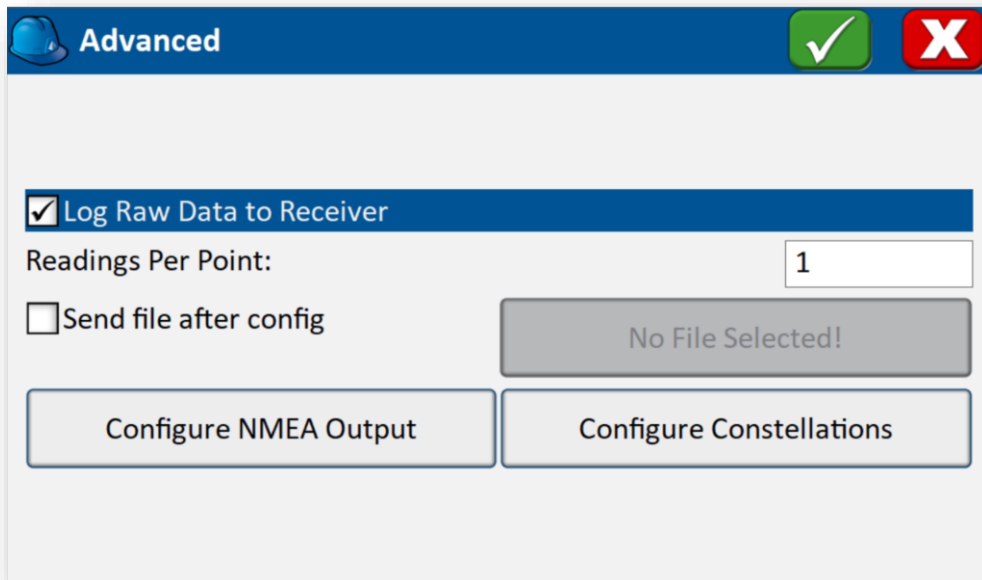


Step 5) – Check the model of your antenna. RTk5 ships with Tallysman 3972XF and Harxon CHX-602A.

Step 6) – Click “Receiver” on the top menu and make sure you have the right antenna type selected. By default the RTk5 tablet will be shipping with the Tallysman TWI3972XF.

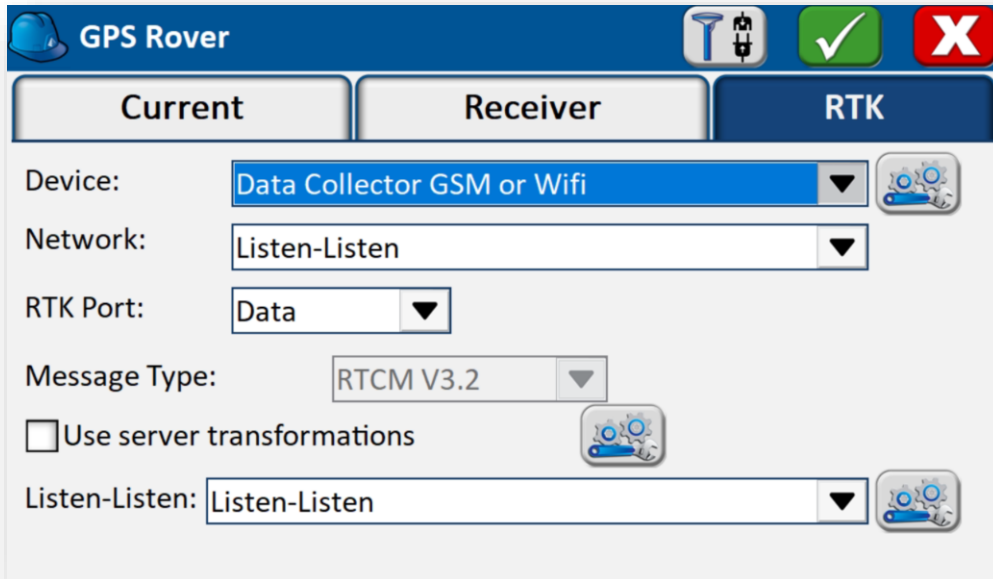


Step 7) – To enable raw logging for post-processing in SurveyGnss: Click "Advanced" and ensure "Log Raw Data to Receiver" is checked.

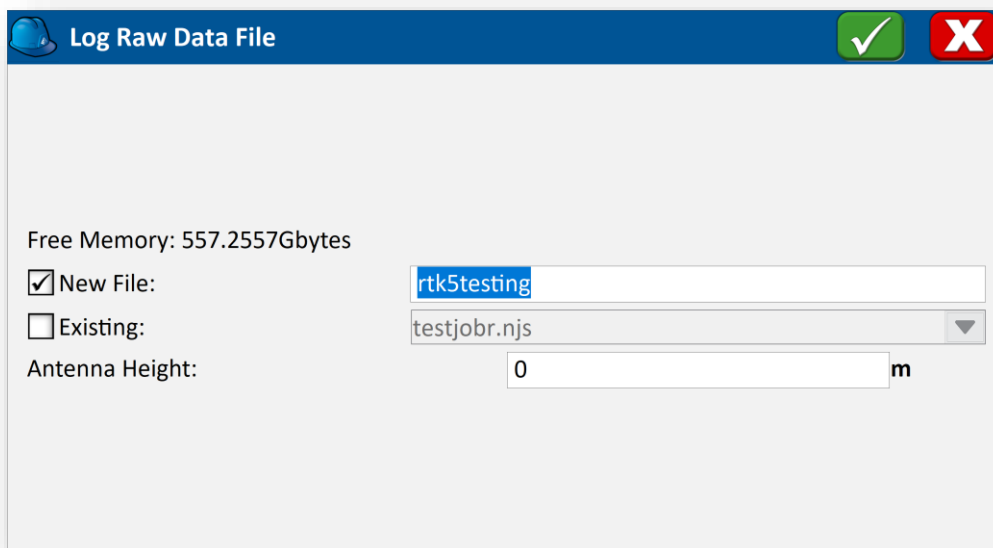


Step 8) – Click “RTK” on the top menu to configure your base station correction stream.

Step 9) – Click the green check button to setup connection between SurvPC and Gama.

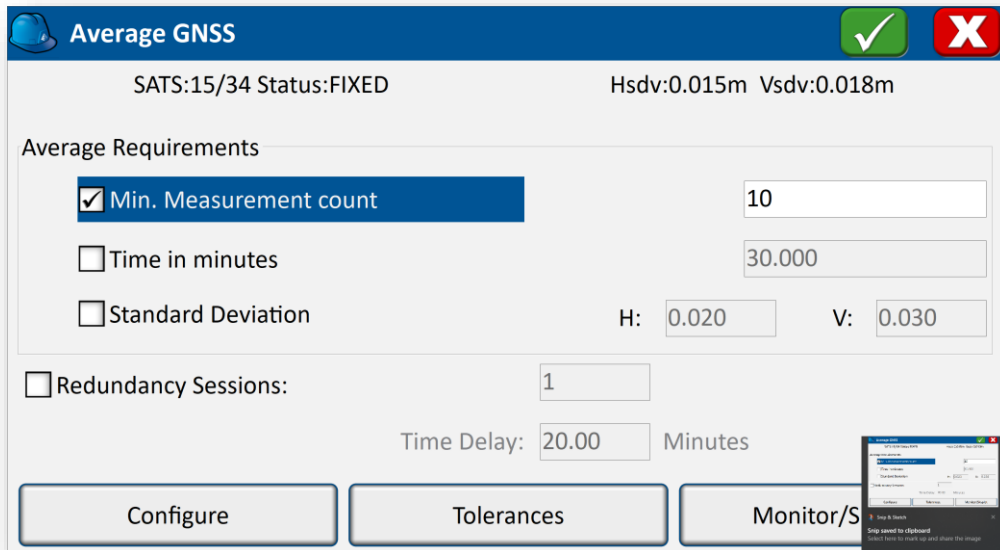


Step 10) – If raw data logging was enabled, give the raw log file an appropriate name. **Ensure that the name is unique, as a raw recording cannot be appended to, it will always overwrite!** SurvPC opens this file as a Stop+Go file, meaning points recorded in the survey routines will be given event markers which indicate the start and stop of an occupation. These event markers are critical for post-processing. SurvPC will command the recorded data to update the antenna height whenever it’s modified.



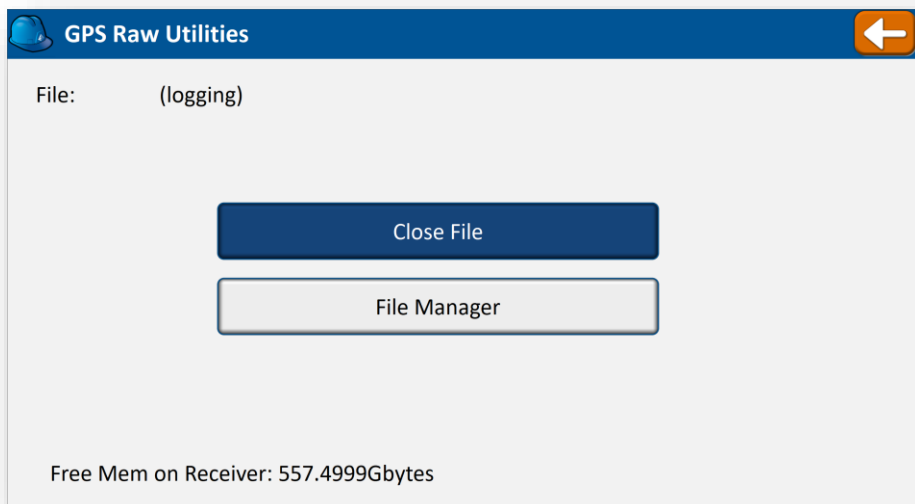


Step 11) – Use SurvPC as normal. If recording data intended to be used for post-processing, ensure best-practices are followed.

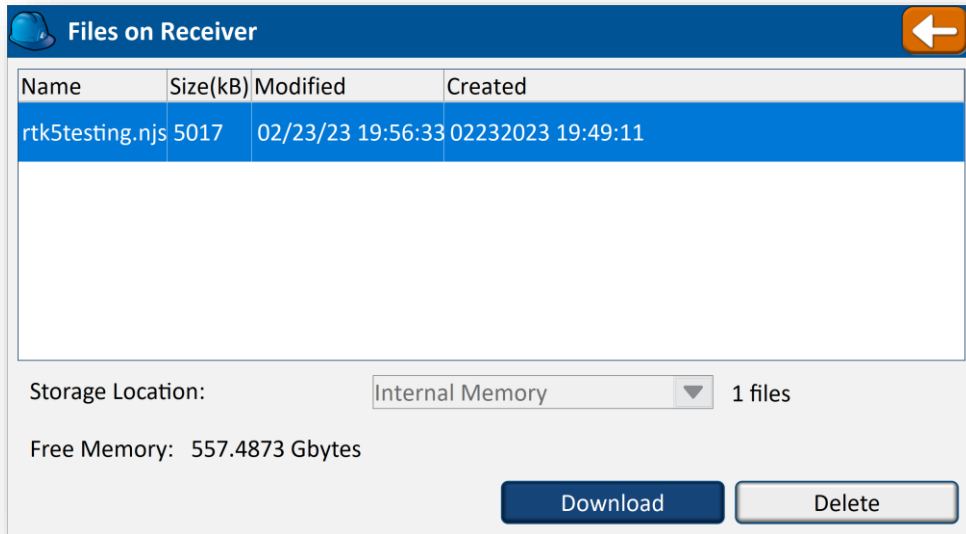


Step 12) – To download raw NJS log, navigate to: Equip -> GPS Utilities -> GPS Raw Utilities.

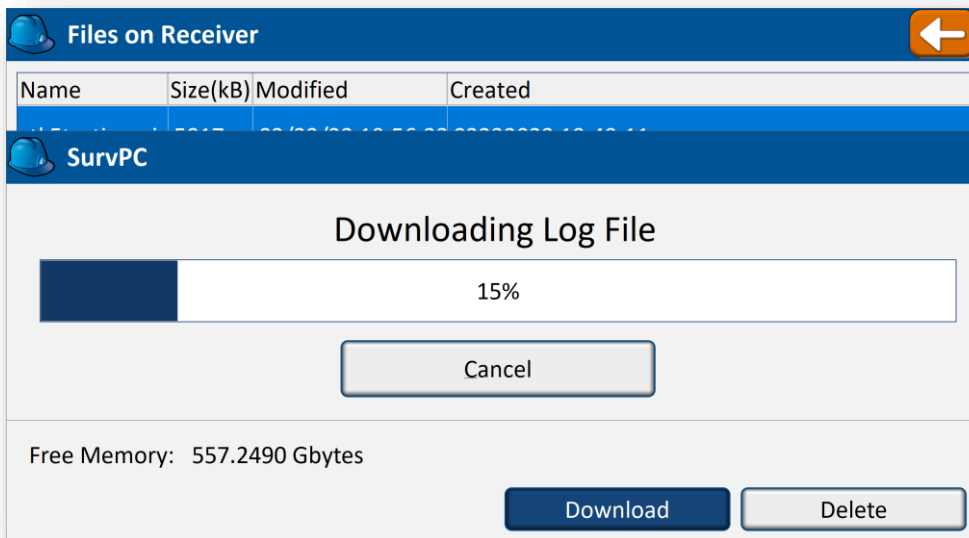
Click “Close File” to ensure the NJS is properly flushed to the disk.



Step 13) – Click File Manager, select the raw file, and click “Download”.



Step 14) – Please wait while the NJS file is downloaded to your job folder.

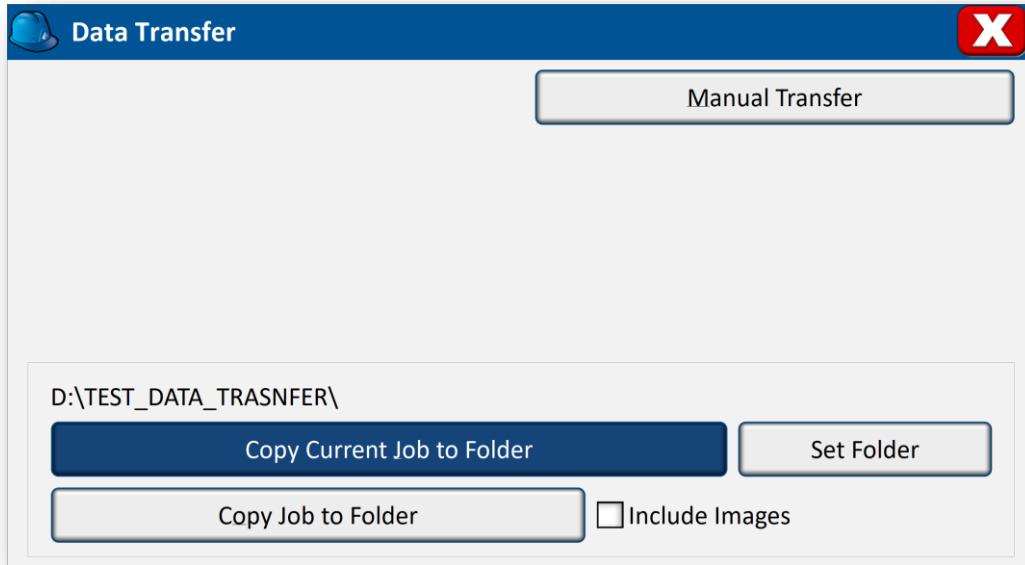


Step 15) – Perform a Data Transfer of the job to removeable media e.g. USB Flash Drive.

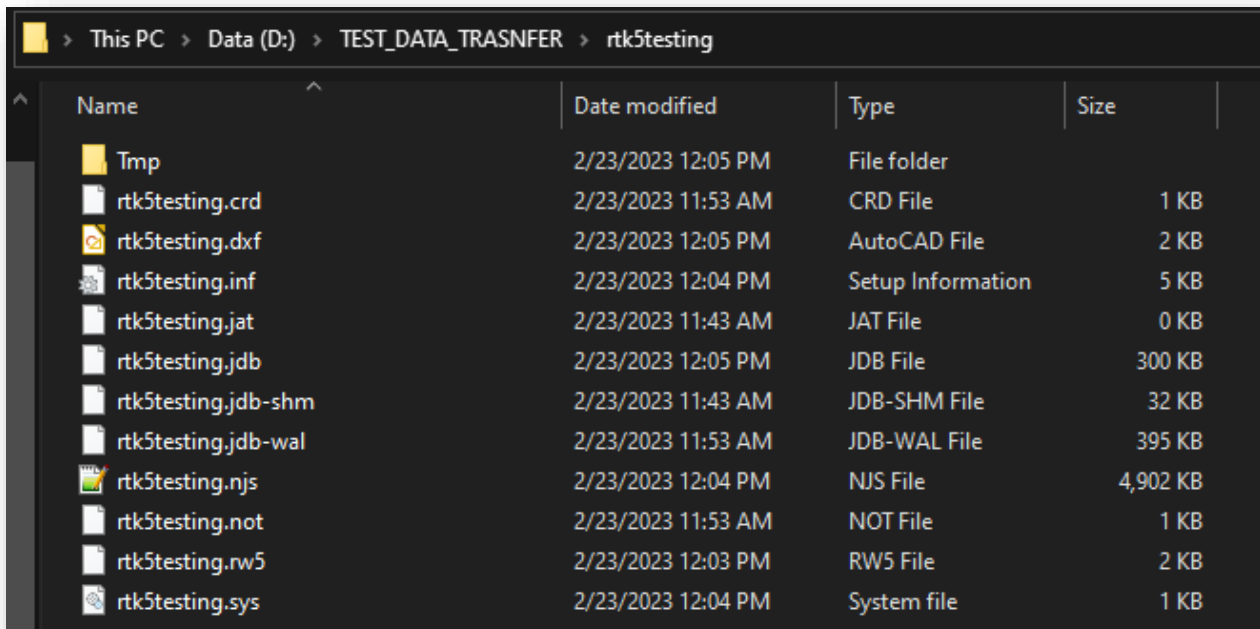
File → Export → Data Transfer

[Set Folder]

[Copy Current Job to Folder]



Step 16) – Exit SurvPC.



## 5 RTk5 GNSS Antennas

RTk5 ships with Tallysman TWI3972XF and Harxon CHX-602A.

The Tallysman antenna is meant for highest accuracy on-the-pole surveys while the Harxon can be directly attached to the RTk5 for extra flexibility and convenience (no survey pole required). Both antennas are graded for high precision RTK accuracy but the Harxon is more susceptible to suffer from multipath effects.



Tallysman TWI3972XF



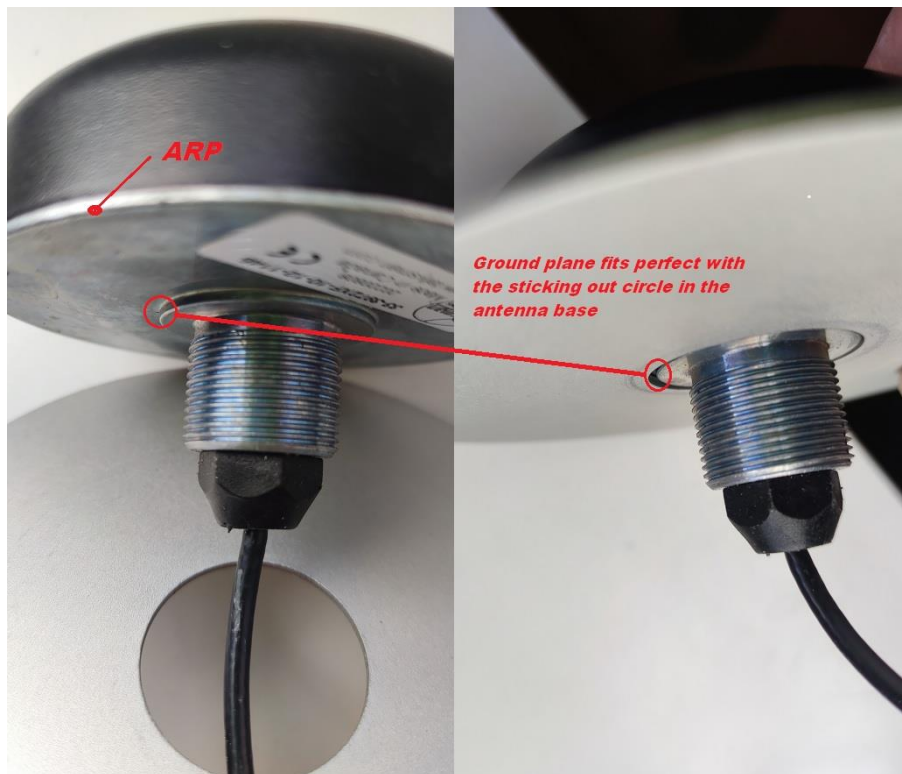
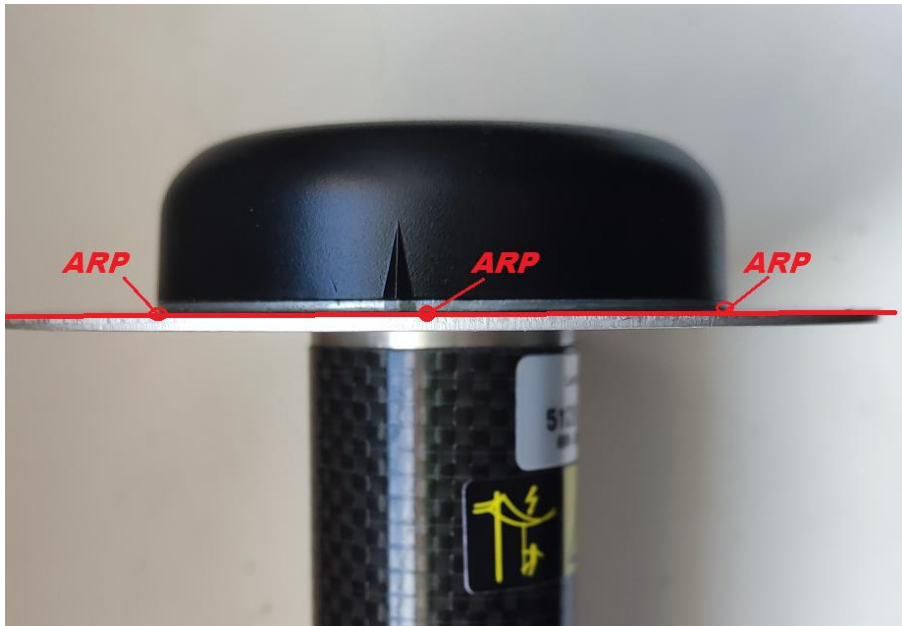
Harxon HXC\_CHX602A

### 5.1. Tallysman TWI3972XF

The Tallysman antenna assembly consists of 2 elements: 1) the antenna and 2) the ground plane.

To install the antenna follow these steps:

- 1) Insert ground plane through 5/8" thread
- 2) Insert antenna cable through the custom survey pole
- 3) Rotate antenna until tightly attached to the survey pole



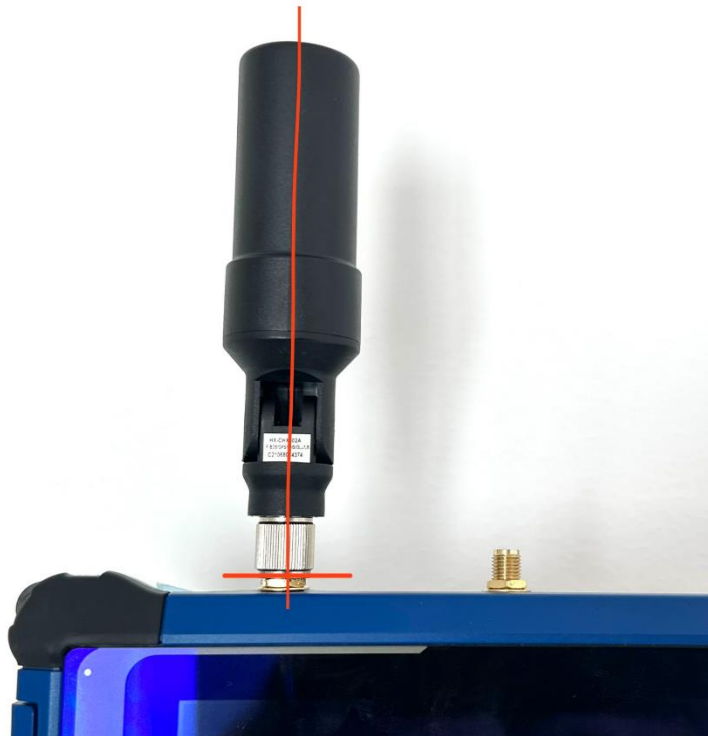
## 5.2. Harxon HXC CHX602A

In order to achieve high accuracy surveys with the Harxon antenna, it is important to understand how to use the device to avoid unwanted offsets:

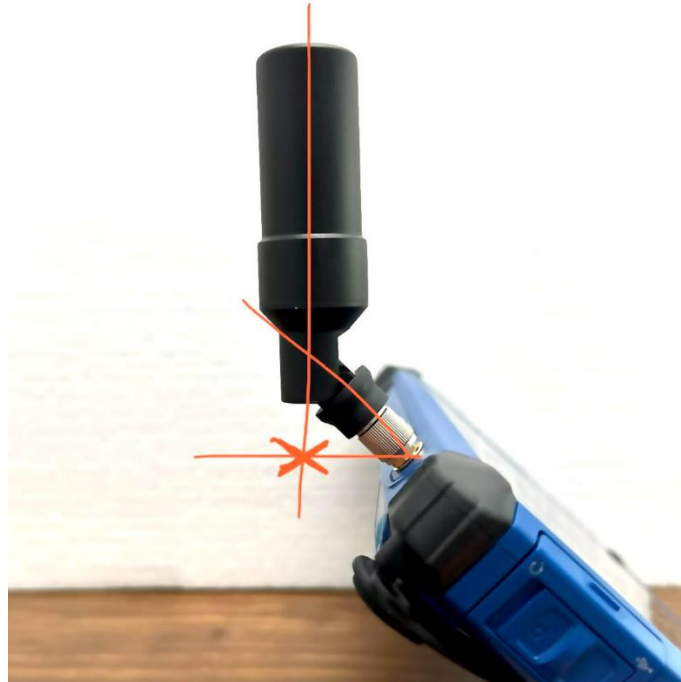
- It is fundamental that the antenna is always vertical with respect to the ground
- The position is reported at the antenna reference point (ARP)

Below are 3 acceptable configurations for surveying. The position reported by the system is tagged with an X in the following images.

### 1) RTk5 is vertical and antenna is vertical



**2) RTk5 is tilted and antenna is vertical**



**3) RTk5 is flat on a surface and antenna is vertical**

*Note that in this case the RTk5 measures the height at the surface.*



## 6 Gama Web UI

### 5.3. Web UI Introduction

The main purpose of Gama UI on the RTk5 is to allow:

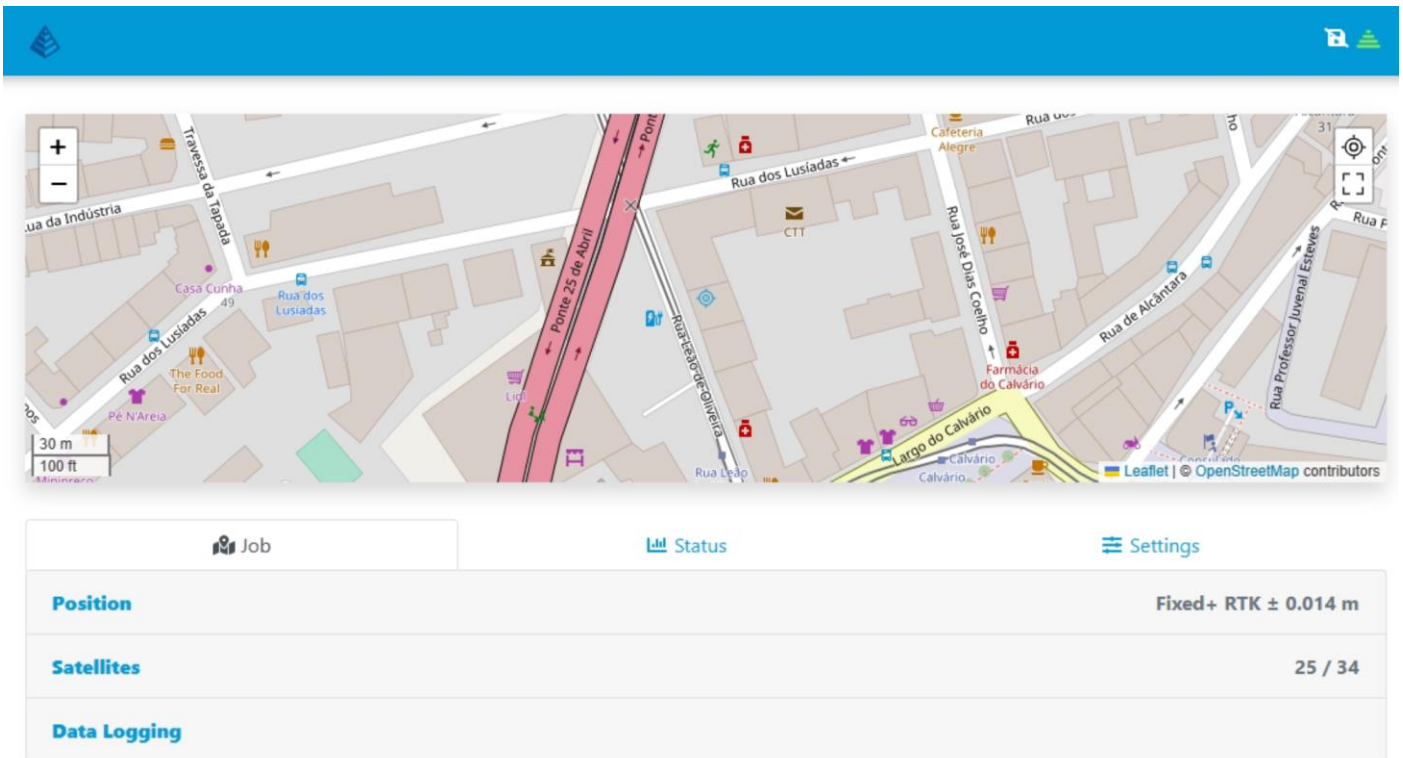
1. Registration of the Gama engine
2. Update Gama and Factory Reset
3. Support and issue tracking
4. Stand-alone tool for using Gama without SurvPC

The Gama Web UI is always accessible on the RTk5 by two options:

1. Double click GNSS UI icon on the Windows Desktop
2. Open a browser and type in 127.0.0.1

The Web UI has 3 main tabs:

- Job
- Status
- Settings





## 5.4. Job

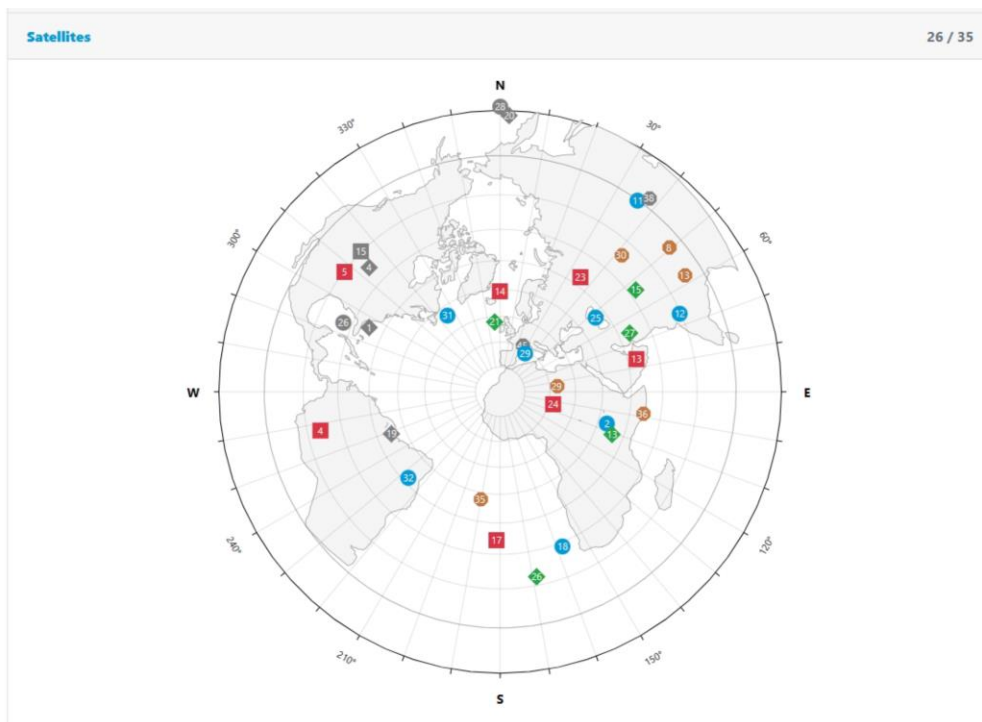
### Job - Position

Monitor detailed information about the GNSS solution, namely status, value, accuracy, differential correction age.

Job		Status	Settings
<b>Position</b>		Fixed+ RTK ± 0.015 m	
Time	14:39:51.40 PM Off by 2.653 s		
Position	38° 42' 19.0666" N 9° 10' 42.7183" W ± 0.015 m		
Elevation	92.490 m ± 0.016 m		
Quality	1.06 PDOP 1 s Latency		

### Job - Satellites

Monitor satellite sky plot, SNR values and satellite usage status.



### Job - Data Logging

Menu for administrating raw data logging independently from SurvPC.

Under this section you can:

- Open and close log files:
  - Static
  - Stop+Go
  - Kinematic
- Log NMEA;
- Delete existing log files;
- Download existing log files (in order to download you must first close the file by unchecking the “active box”);
- Add “static” and “moving” events to active Stop+Go log files.

You can log multiples files simultaneously. The WebUI is intelligent enough to only add Stop+Go event markers to an open Stop+Go log file.

**Data Logging**

Internal

Active	Name	Type	Status	Size	Events	Created	Modified	Actions
<input checked="" type="checkbox"/>	230206-145214-NMEA	NMEA	-	89.12 KB	0	2023-02-06 14:52:35	2023-02-06 14:53:42	<input type="button" value="Download"/> <input type="button" value="Delete"/>
<input checked="" type="checkbox"/>	230206-145222-Stop-Go	Stop-Go	Kinematic	601.64 KB	1	2023-02-06 14:52:43	2023-02-06 14:53:42	<input type="button" value="Download"/> <input type="button" value="Delete"/>
<input type="checkbox"/>	230206-145232-Static	Static	Static	89.84 KB	0	2023-02-06 14:52:53	2023-02-06 14:53:01	<input type="button" value="Download"/> <input type="button" value="Delete"/>

**New Log File**

File Name

Static

Internal

Rod height Changed

Meters

Event

## 5.5. Status

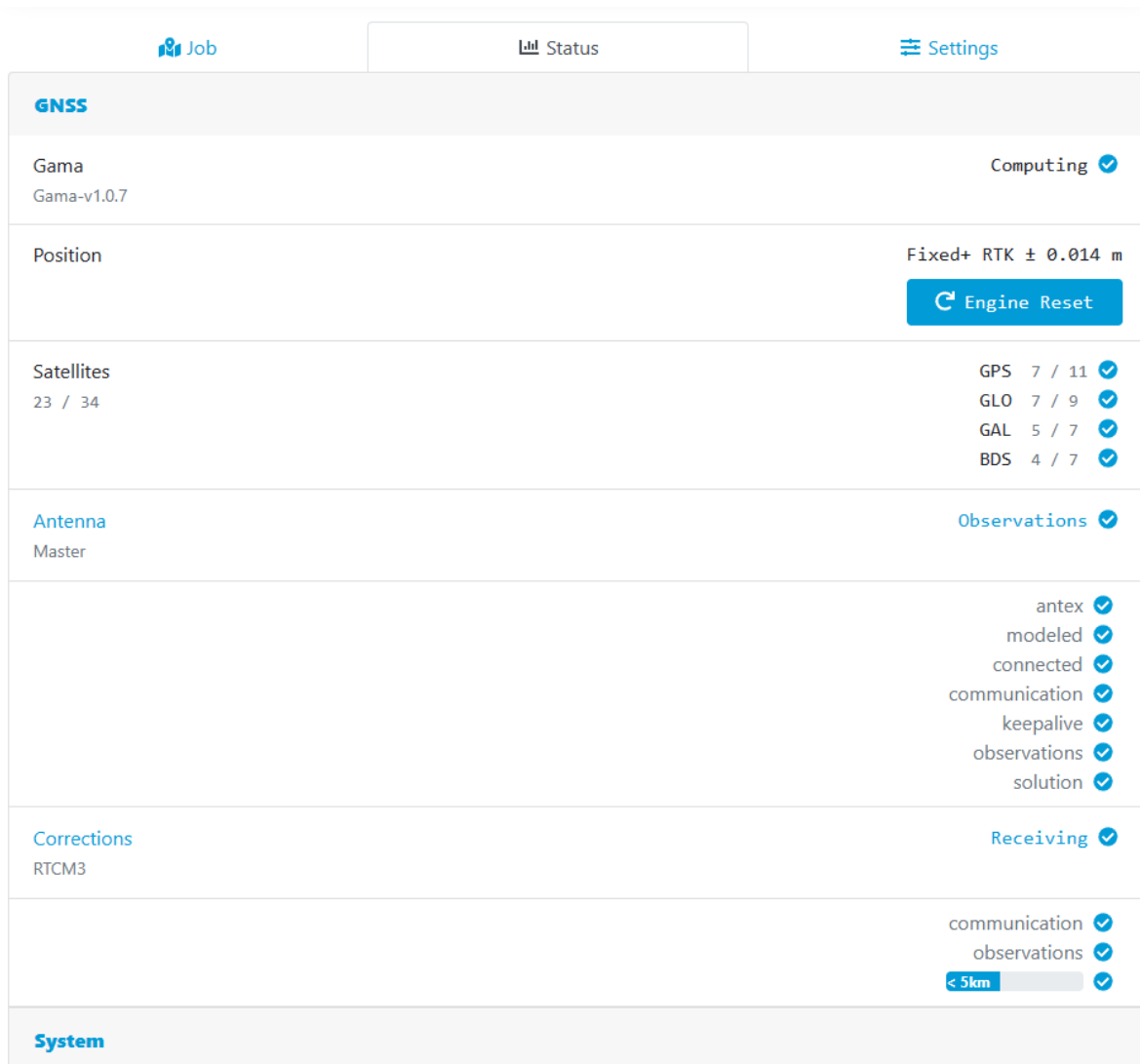
Monitor overall status of the Gama GNSS system and issue track potential problems.

### Status – GNSS

Monitor detailed information about the GNSS status and data flow.

Here you can also issue a Reset of the Gama engine.

In this section you can inspect detailed diagnostics about the GNSS system, namely if the receiver is powered on and connected, if it is tracking and receiving observations, if Gama is running correctly, etc.

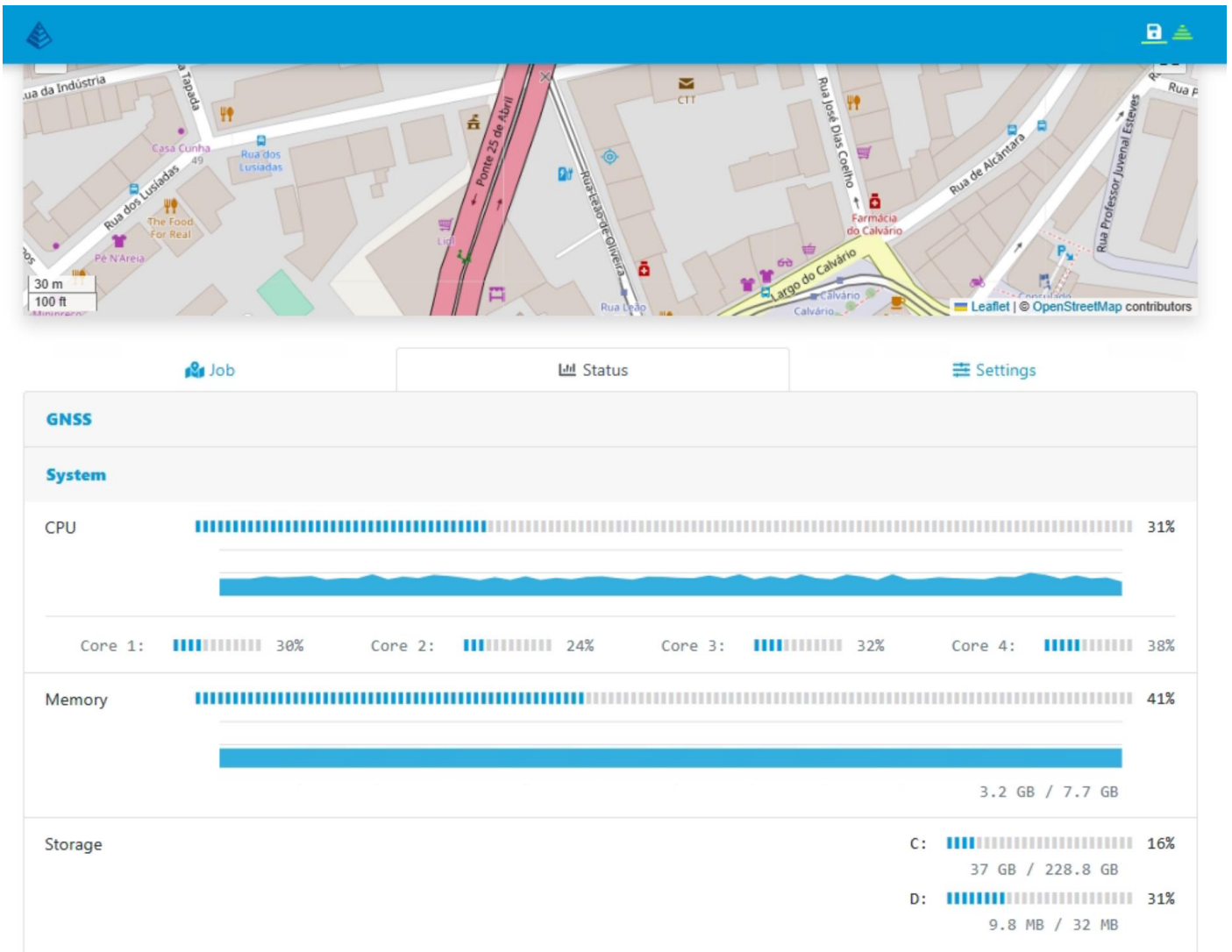


The screenshot shows the 'Status' tab of the Gama GNSS interface. It features a navigation bar with 'Job', 'Status', and 'Settings' tabs. The main content area is divided into several sections:

- GNSS**: Shows 'Gama' (Gama-v1.0.7) with a status of 'Computing' and a checkmark. Below it, 'Position' is 'Fixed+ RTK ± 0.014 m' with an 'Engine Reset' button.
- Satellites**: Shows '23 / 34' satellites. A list of satellite systems is shown with their counts and status: GPS (7 / 11), GLO (7 / 9), GAL (5 / 7), and BDS (4 / 7), all with checkmarks.
- Antenna**: Shows 'Master' antenna. A list of antenna-related status items is shown with checkmarks: antex, modeled, connected, communication, keepalive, observations, and solution.
- Corrections**: Shows 'RTCM3' corrections with a status of 'Receiving'. A list of correction-related status items is shown with checkmarks: communication, observations, and a distance indicator '< 5km'.
- System**: A section header at the bottom of the interface.

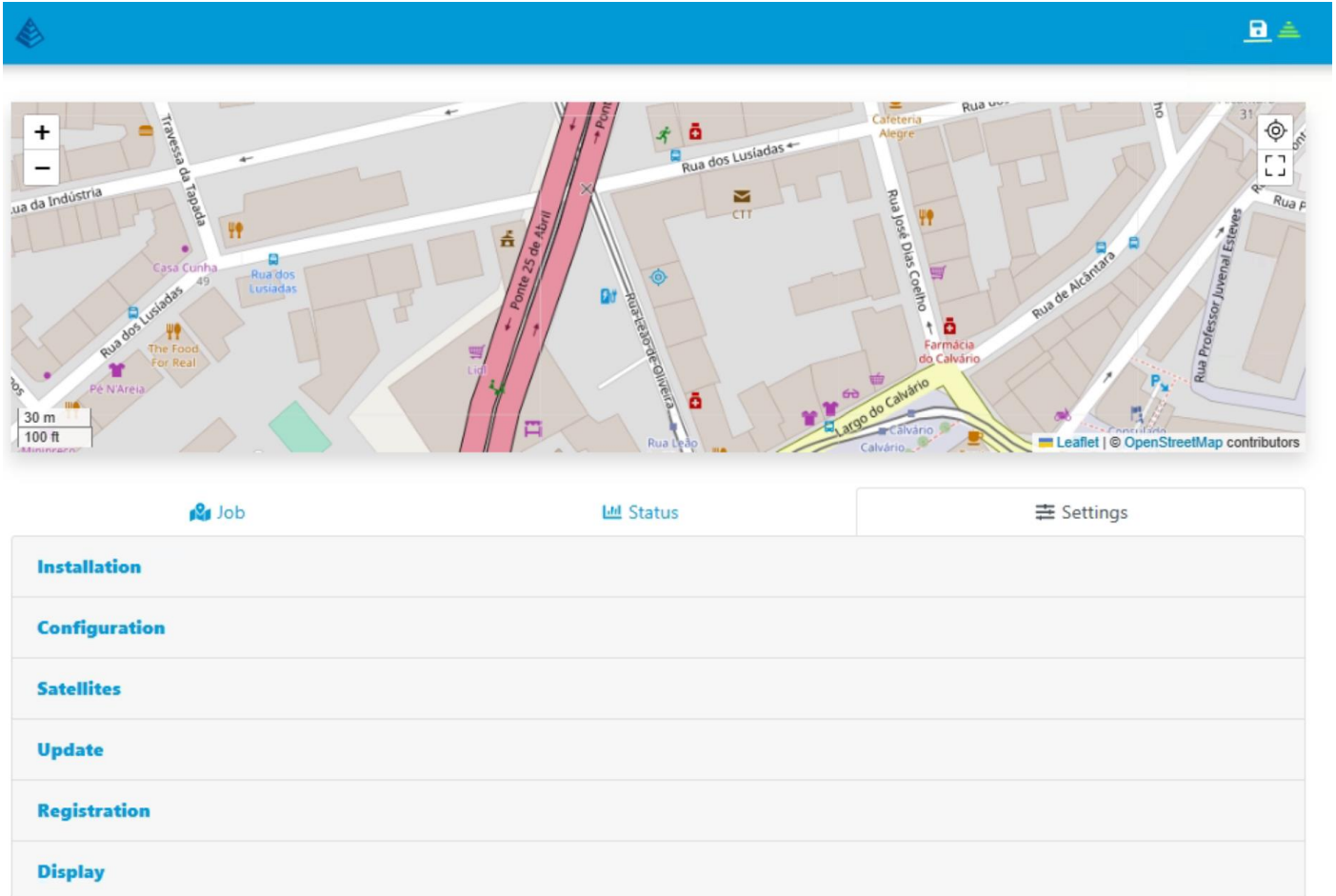
### Status – System

Monitor detailed information about RTk5 CPU, RAM memory and internal storage.



## 5.6. Settings

Configure Gama via the Web UI.



### Settings – Installation

- Configure antenna type and antenna serial number.

### Settings – Configuration

- Configure mode (Rover/Base);
- Set GNSS data rate;
- Set rod height.

### Settings – Satellites

- Configure satellite elevation mask;

- Enable/disable GNSS constellations;
- Exclude satellites.

### **Settings – Update**

- Update Gama engine – see section 3 - Updating Gama;
- Perform Factory Reset.

### **Settings – Registration**

- Manage Gama engine license and registration
- The Gama-RTk5 license modules are:
  - Basic - Allows recording of Raw Data (NJS) and Communication with SurvPC
  - RTK - Allows usage of corrections streams to go RTK-Fixed
  - North America - Allows usage of RTK within North America

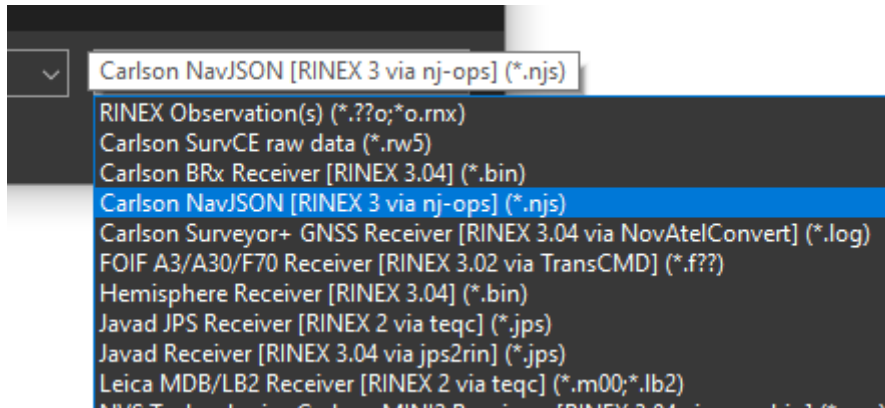
### **Settings – Display**

- Configure display settings and units (metric/imperial).

## 7 Importing to SurveyGNSS

To post-process Gama raw data in SurveyGNSS ensure raw data logging is enabled in SurvPC or via the Web UI.

SurveyGNSS can directly import raw NJS files (SurveyGNSS version 2.3.5 and above), no special procedure is required.

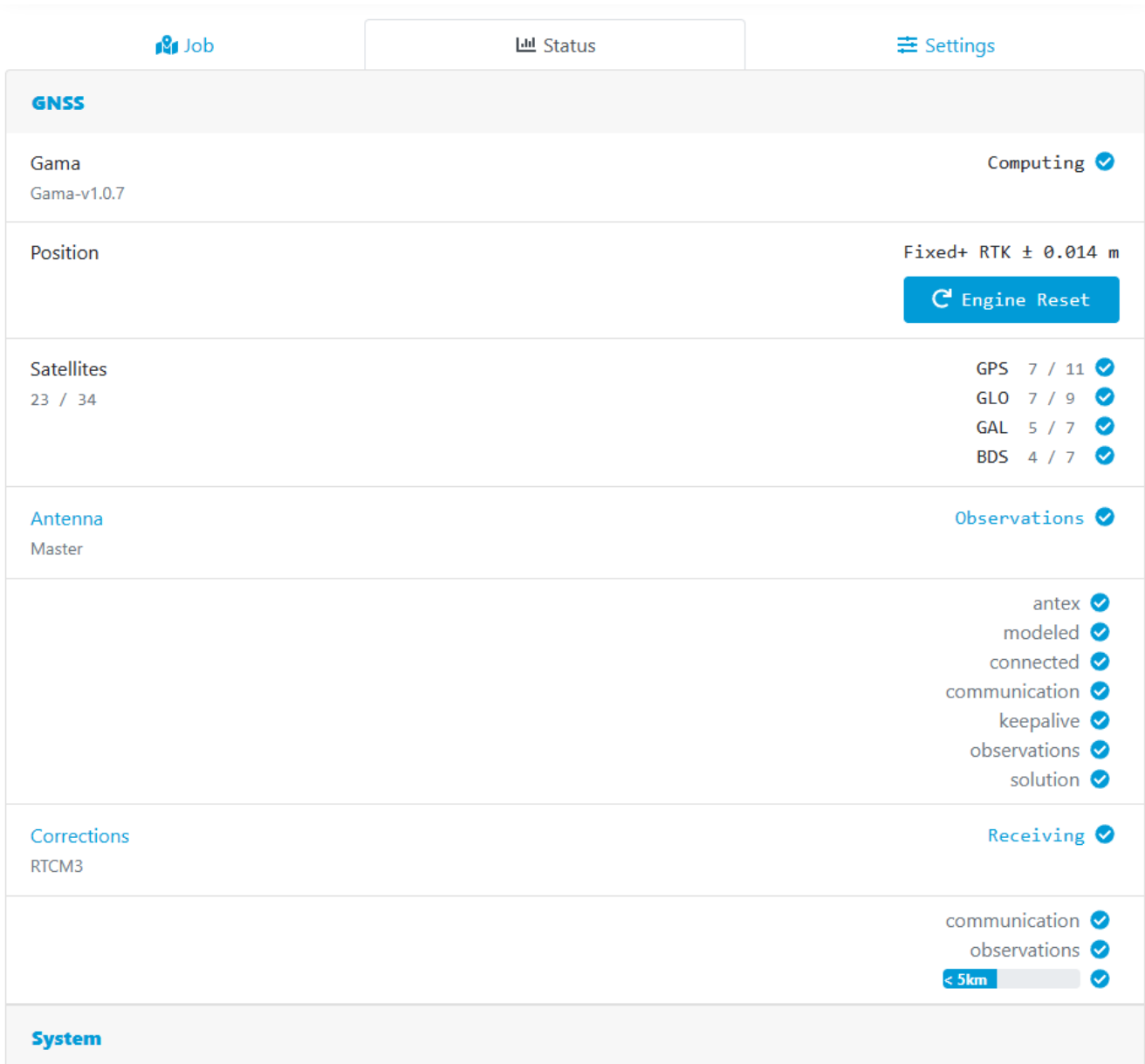


## 8 Troubleshooting

If Gama becomes unresponsive or is not operating as expected follow these steps:

- 1) Open Gama Web UI using the Desktop icon (alternatively open a browser on the RTk5 tablet and type in 127.0.0.1).
- 2) Inspect Status tab on the Web UI and check if all status are OK.

Normally, all status be in blue colour as shown below. You see any item in red continue reading below for troubleshooting.






The screenshot displays the 'Status' tab of the Gama Web UI. At the top, there are three navigation tabs: 'Job', 'Status', and 'Settings'. The 'Status' tab is active. Below the tabs, the interface is organized into several sections:

- GNSS**: This section contains several rows of data:
  - Gama**: Version 'Gama-v1.0.7' with a status of 'Computing' (blue checkmark).
  - Position**: Shows 'Fixed+ RTK ± 0.014 m' and includes an 'Engine Reset' button.
  - Satellites**: Shows '23 / 34' satellites. A breakdown is provided: GPS (7 / 11), GLO (7 / 9), GAL (5 / 7), and BDS (4 / 7), all with blue checkmarks.
  - Antenna**: Shows 'Master' antenna with a status of 'Observations' (blue checkmark). Below this, a list of antenna-related parameters is shown, all with blue checkmarks: antex, modeled, connected, communication, keepalive, observations, and solution.
  - Corrections**: Shows 'RTCM3' corrections with a status of 'Receiving' (blue checkmark). Below this, 'communication' and 'observations' are listed with blue checkmarks, and a distance indicator shows '< 5km' with a blue checkmark.
- System**: A section at the bottom of the status area.



### 8.1 Antenna or cable connection problem

If antenna shows “No observation data” status (in yellow) but Gama shows “Idle” (in yellow) then double check your antenna connection and cable.

 Job
 Status
 Settings

GNSS	
Gama Gama-v1.0.5	Idle <span style="color: yellow;">⚠</span>
Position	Invalid <span style="background-color: #007bff; color: white; padding: 2px 5px; border-radius: 3px; display: inline-block;">↻ Engine Reset</span>
Satellites 0 / 0	GPS 0 / 0 <span style="color: red;">✖</span> GLO 0 / 0 <span style="color: red;">✖</span> GAL 0 / 0 <span style="color: red;">✖</span> BDS 0 / 0 <span style="color: red;">✖</span>
Antenna Master	No observation data <span style="color: yellow;">⚠</span>
	antex <span style="color: blue;">✔</span> modeled <span style="color: blue;">✔</span> connected <span style="color: blue;">✔</span> communication <span style="color: blue;">✔</span> keepalive <span style="color: blue;">✔</span> observations <span style="color: red;">✖</span> solution <span style="color: blue;">✔</span>
Corrections	Receiving <span style="color: blue;">✔</span>
	communication <span style="color: blue;">✔</span> observations <span style="color: blue;">✔</span>
System	

Ensure you have the GNSS antenna correctly connected to the RTk5.

The GNSS antenna connector is the left SMA connector on top of the device:



RTk5 ships with Tallysman 3972XF and Harxon CHX-602A.



Tallysman TWI3972XF




















































Harxon HXC\_CHX602A

## 8.2 Internal GNSS receiver connection problem

In the event a Windows update takes control of the built-in GNSS, it will block Gama from establishing a connection to the internal GNSS Receiver.

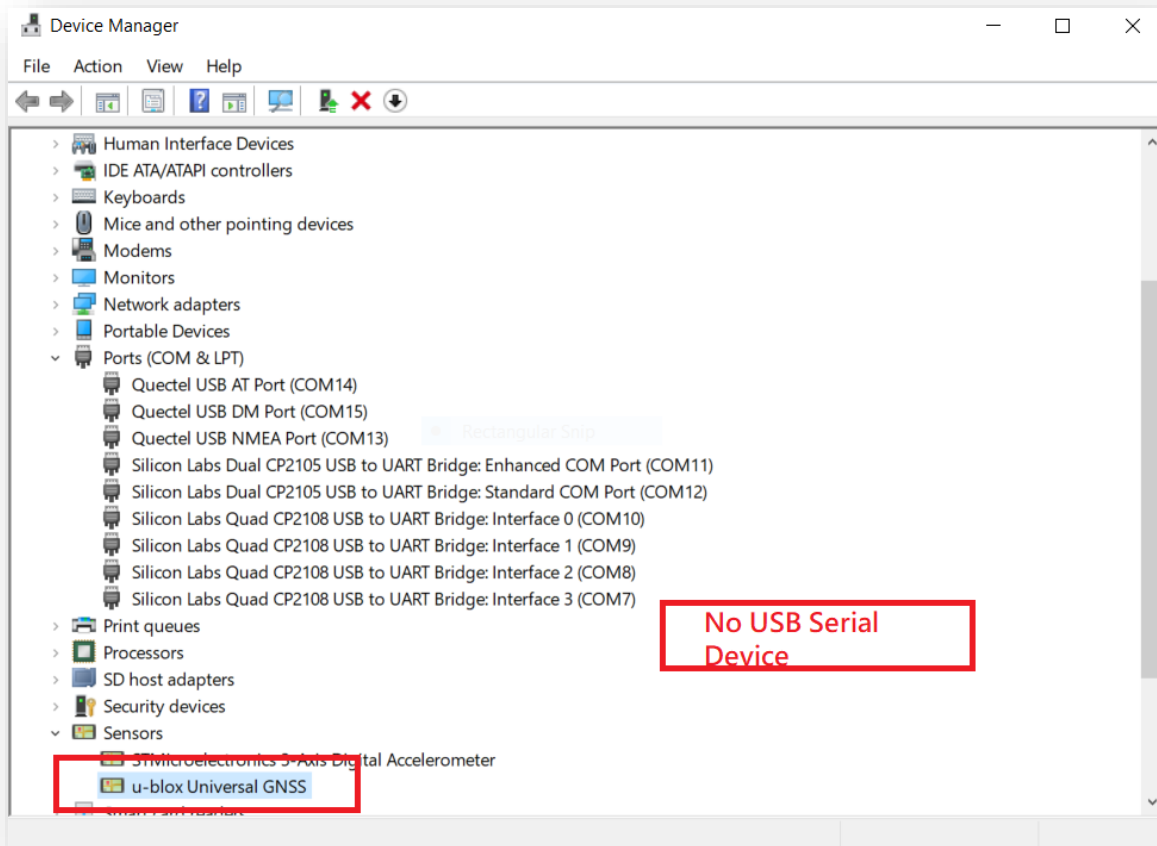
In this case, the “Antenna” field will show the “Disconnected” status. Please follow these steps to identify and resolve this problem.

 Job
 Status
 Settings

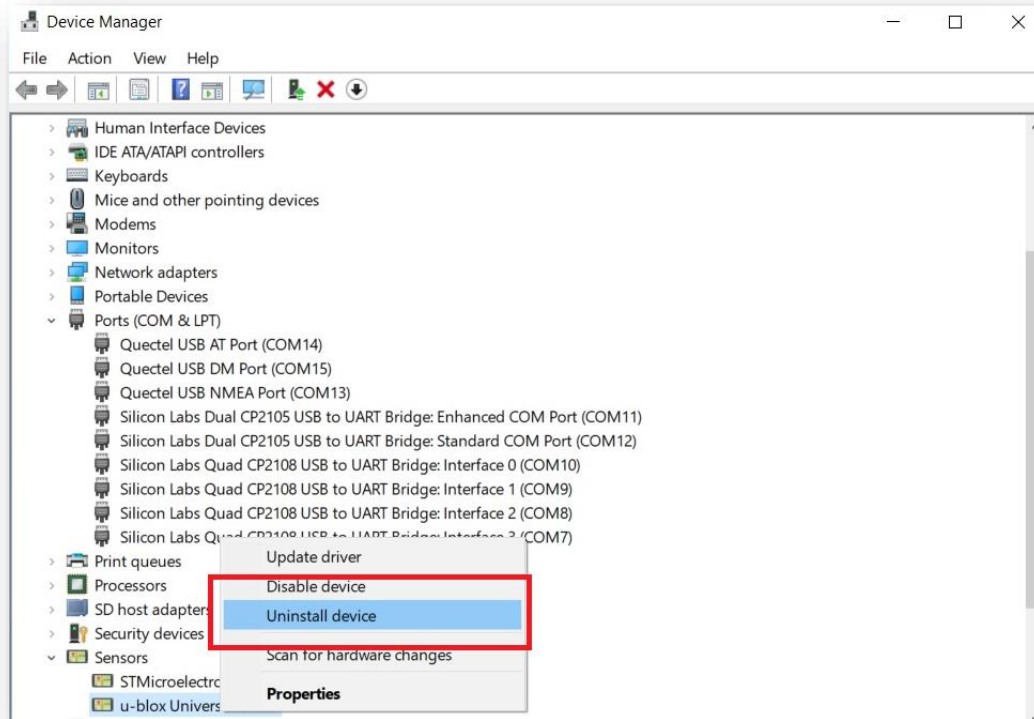
GNSS															
Gama <small>Gama-v1.0.7</small>	Idle  Unregistered 														
Position	Invalid  <div style="text-align: right;"><a href="#" style="background-color: #007bff; color: white; padding: 2px 10px; border-radius: 4px;">↻ Engine Reset</a></div>														
Satellites <small>0 / 0</small>	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="text-align: right;">GPS</td><td style="text-align: center;">0 / 0</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">GLO</td><td style="text-align: center;">0 / 0</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">GAL</td><td style="text-align: center;">0 / 0</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">BDS</td><td style="text-align: center;">0 / 0</td><td style="text-align: left;"></td></tr> </table>	GPS	0 / 0		GLO	0 / 0		GAL	0 / 0		BDS	0 / 0			
GPS	0 / 0														
GLO	0 / 0														
GAL	0 / 0														
BDS	0 / 0														
Antenna <small>Master</small>	Disconnected 														
	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="text-align: right;">antex</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">modeled</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">connected</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">communication</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">keepalive</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">observations</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">solution</td><td style="text-align: left;"></td></tr> </table>	antex		modeled		connected		communication		keepalive		observations		solution	
antex															
modeled															
connected															
communication															
keepalive															
observations															
solution															
Corrections <small>None</small>	No license module 														
	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="text-align: right;">communication</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">observations</td><td style="text-align: left;"></td></tr> <tr><td style="text-align: right;">[Progress Bar]</td><td style="text-align: left;"></td></tr> </table>	communication		observations		[Progress Bar]									
communication															
observations															
[Progress Bar]															
System															

Open Windows “Device Manager” (click Start and type “Device Manager”).

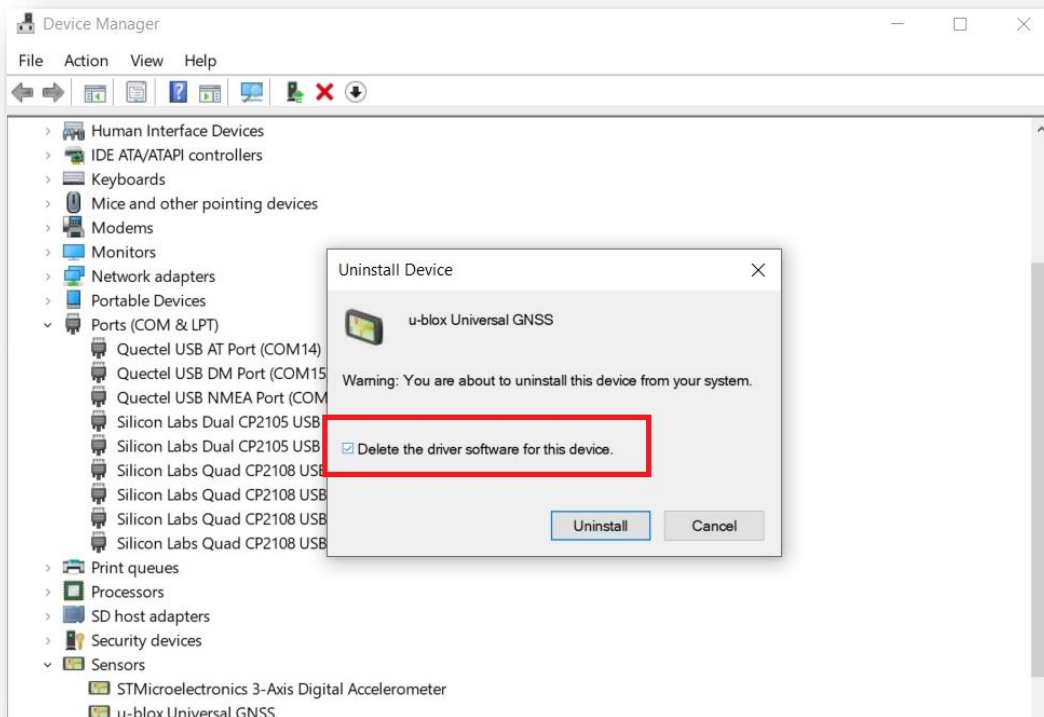
If you see “u-blox Universal GNSS” under “Sensors” than your RTk5 has the wrong driver installed. Follow the next steps to resolve the issue.



1) Right click on “u-blox Universal GNSS” and click “Uninstall device”.

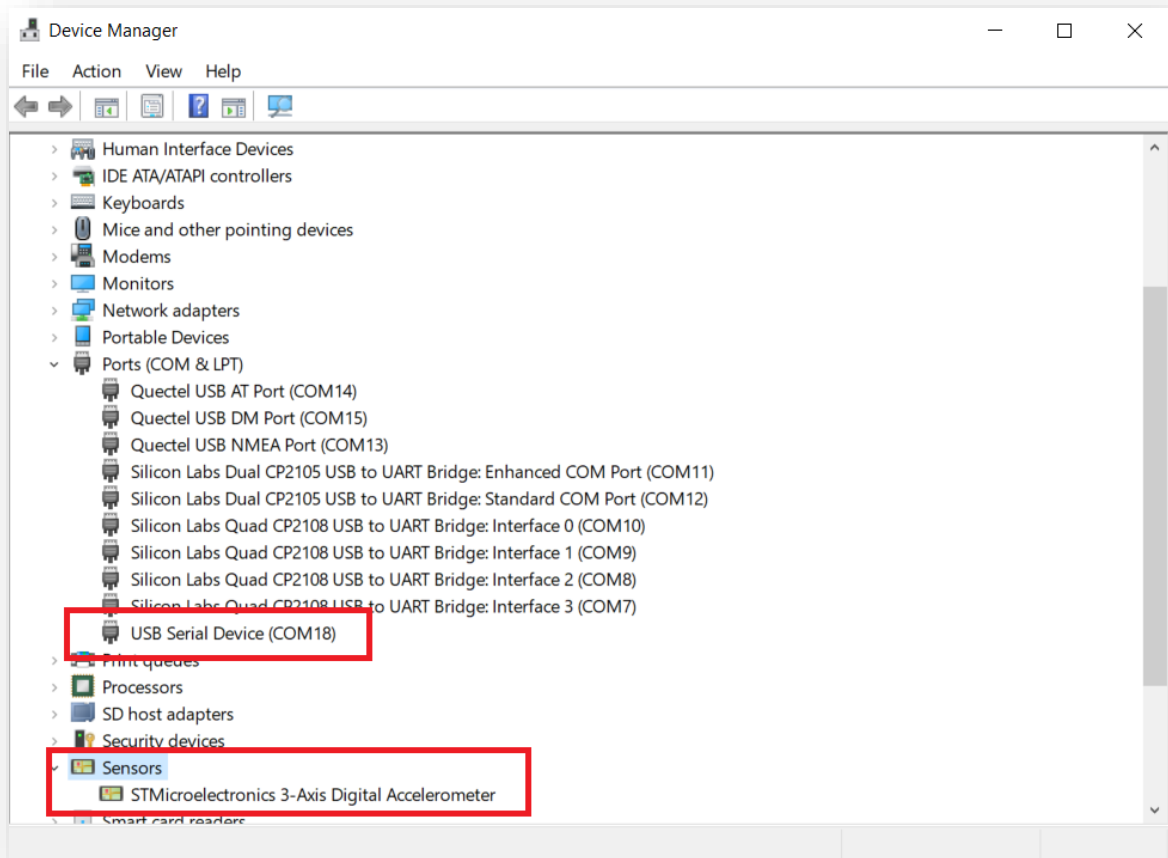


2) Click “Uninstall” to confirm.



3) Shutdown Windows (do not restart, make sure to shutdown).




4) Power on RTk5 and open “Device Manager”. You should now see the following:




















### 8.3 Gama is unregistered

If Gama is not fixing, if you cannot connect SurvPC to Gama, or some features appear disabled (not able to log NJS raw data) make sure Gama is correctly Registered. To Register Gama see chapter 2 - Gama RTK Engine Registration.




Note that Gama may become unregistered due to data corruption or by executing the Fresh Installation procedure on an existing install of Gama, which will delete the active registration from the device.












































 Job
 Status
 Settings

<b>GNSS</b>													
Gama <small>Gama-v1.0.4</small>	Idle  Unregistered 												
Position	Invalid <span style="background-color: #007bff; color: white; padding: 2px 5px; border-radius: 3px;"> Engine Reset</span>												
Satellites <small>0 / 0</small>	<table style="width: 100%; border: none;"> <tr><td style="padding: 2px 5px;">GPS</td><td style="padding: 2px 5px;">0 / 0</td><td style="padding: 2px 5px;"></td></tr> <tr><td style="padding: 2px 5px;">GLO</td><td style="padding: 2px 5px;">0 / 0</td><td style="padding: 2px 5px;"></td></tr> <tr><td style="padding: 2px 5px;">GAL</td><td style="padding: 2px 5px;">0 / 0</td><td style="padding: 2px 5px;"></td></tr> <tr><td style="padding: 2px 5px;">BDS</td><td style="padding: 2px 5px;">0 / 0</td><td style="padding: 2px 5px;"></td></tr> </table>	GPS	0 / 0		GLO	0 / 0		GAL	0 / 0		BDS	0 / 0	
GPS	0 / 0												
GLO	0 / 0												
GAL	0 / 0												
BDS	0 / 0												
Antenna <small>Master</small>	Disconnected 												
Corrections	No license module 												
<b>System</b>													

### 8.4 Wrong antenna type

If you forgot to set the antenna type or selected a wrong antenna then Gama will not be able to apply antex calibration (causing vertical offsets) and will not be able to correctly model the antenna SNR response (leading to sub-optimal RTK performance).

 Job
 Status
 Settings

<b>GNSS</b>															
Gama Gama-v1.0.3	Computing 														
Position	Float RTK ± 0.409 m <div style="text-align: right; margin-top: 5px;"> Engine Reset</div>														
Satellites 16 / 28	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="width: 100px;">GPS</td><td style="text-align: center;">8 / 8</td><td style="text-align: right;"></td></tr> <tr><td>GLO</td><td style="text-align: center;">8 / 9</td><td style="text-align: right;"></td></tr> <tr><td>GAL</td><td style="text-align: center;">0 / 4</td><td style="text-align: right;"></td></tr> <tr><td>BDS</td><td style="text-align: center;">0 / 7</td><td style="text-align: right;"></td></tr> </table>	GPS	8 / 8		GLO	8 / 9		GAL	0 / 4		BDS	0 / 7			
GPS	8 / 8														
GLO	8 / 9														
GAL	0 / 4														
BDS	0 / 7														
Antenna Master	Observations 														
	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="width: 100px;">antex</td><td style="text-align: right;"></td></tr> <tr><td>modeled</td><td style="text-align: right;"></td></tr> <tr><td>connected</td><td style="text-align: right;"></td></tr> <tr><td>communication</td><td style="text-align: right;"></td></tr> <tr><td>keepalive</td><td style="text-align: right;"></td></tr> <tr><td>observations</td><td style="text-align: right;"></td></tr> <tr><td>solution</td><td style="text-align: right;"></td></tr> </table>	antex		modeled		connected		communication		keepalive		observations		solution	
antex															
modeled															
connected															
communication															
keepalive															
observations															
solution															
Corrections	Receiving 														
	<table style="width: 100%; border-collapse: collapse;"> <tr><td style="width: 100px;">communication</td><td style="text-align: right;"></td></tr> <tr><td>observations</td><td style="text-align: right;"></td></tr> </table>	communication		observations											
communication															
observations															
<b>System</b>															

If you confirm you did select the right antenna type but still observe a red indicator for “antex” or “model” then you may be using a new type of antenna that is not yet fully supported by Gama. In this case please reach out to your Carlson Software Support point of contact.



### 8.5 Baseline degrading performance

If the selected base has a baseline too long, Gama will perform have sub-optimal RTK performance.

VRS is unique in that the base observations are synthetically generated. Ensure you are within the VRS network.

<p>Corrections RTCM3</p> <p>Receiving ✓</p> <p>communication ✓ observations ✓ &lt; 5km ✓</p>	<p>Corrections RTCM3</p> <p>Receiving ✓</p> <p>communication ✓ observations ✓ &lt; 15km ✓</p>
<p>Corrections RTCM3</p> <p>Receiving ⚠</p> <p>communication ✓ observations ✓ &gt; 25km ⚠</p>	<p>Corrections RTCM3</p> <p>Baseline ✖</p> <p>communication ✓ observations ✓ &gt; 45km ✖</p>
<p>Corrections RTCM3</p> <p>Receiving ✓</p> <p>communication ✓ observations ✓ VRS ✓</p>	

Review the selected Base and ensure the distance is an appropriate length.

## 8.6 Hard crash

If a hard crash occurred but the Web UI is still responsive, you see should see a status like this:

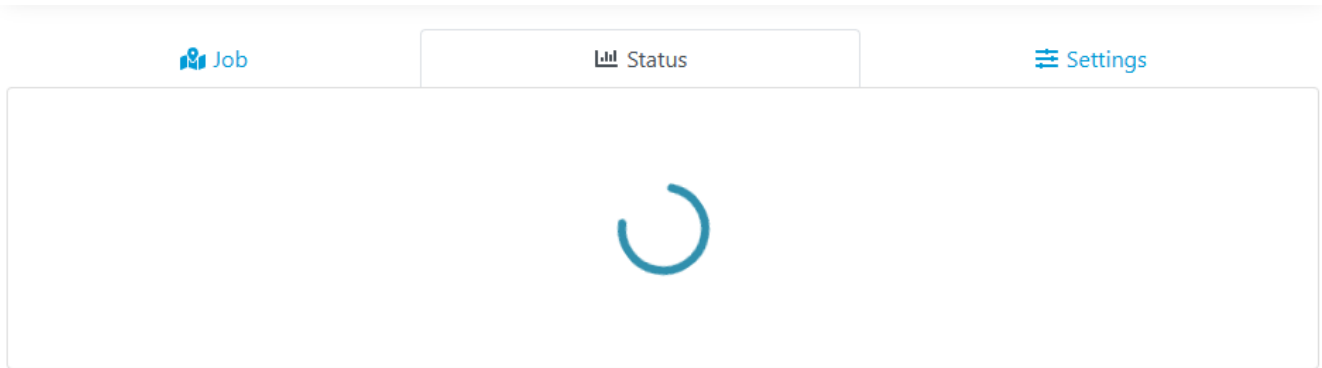
Job		Status		Settings	
<b>GNSS</b>					
Gama	20230204.1	No Response	✖		
Position		Invalid	<input type="button" value="Engine Reset"/>		
Satellites	0 / 0	GPS	0 / 0	✖	
		GLO	0 / 0	✖	
		GAL	0 / 0	✖	
		BDS	0 / 0	✖	
Antenna	Master	Disconnected	✖		
Corrections		None	⌵		
<b>System</b>					

Follow these steps:

- 1) Open Windows File Explorer and type in the following path “C:\ProgramData\Gama\logs”;
- 2) Copy all logs and forward them to your Carlson Software Support point of contact;
- 3) Reboot RTk5 tablet.

## 8.7 Web UI unresponsive

If the Gama Web UI is unresponsive, you may observe the following:



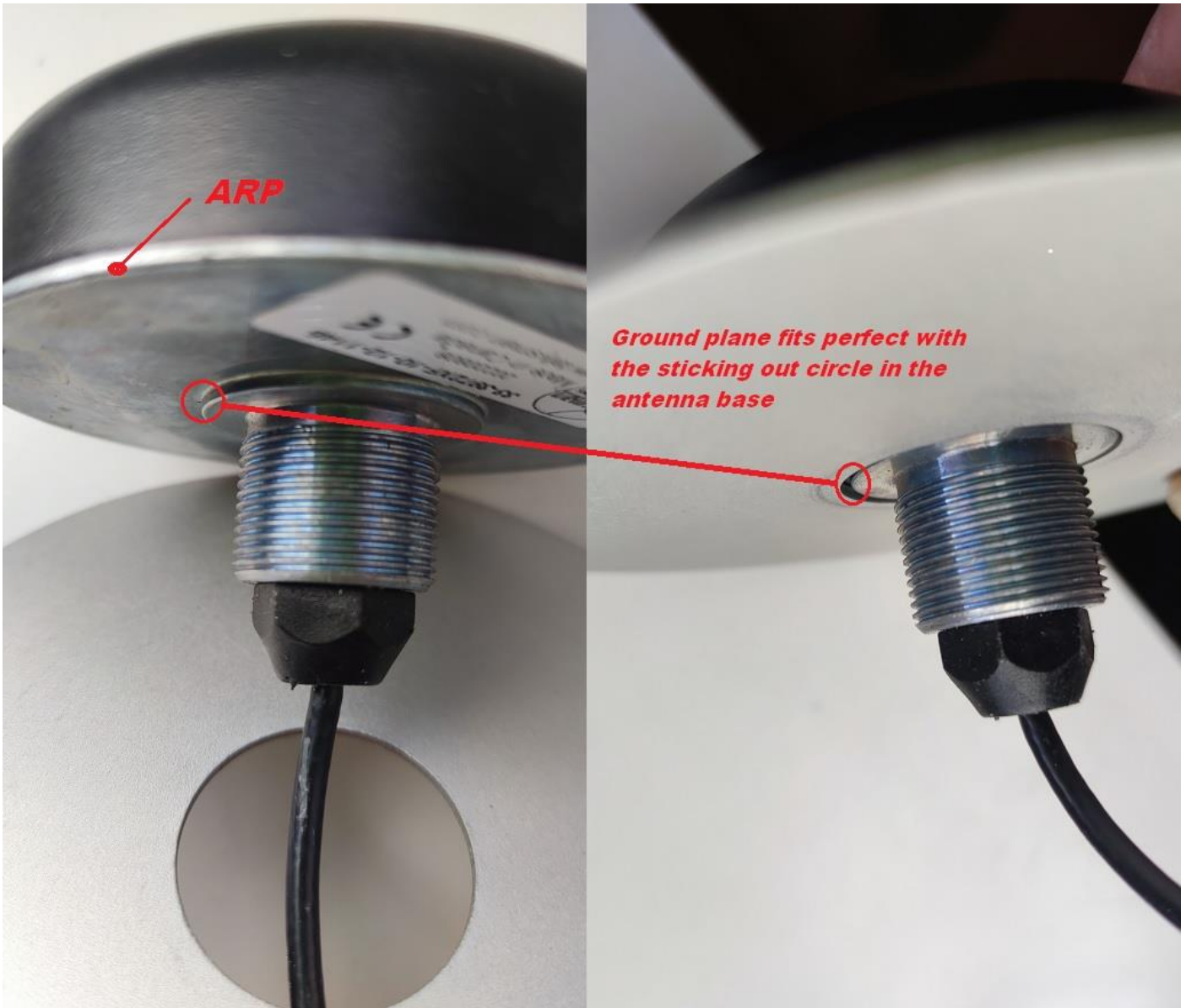
This is expected behaviour after updating Gama. Please wait and refresh (press F5).

If the Web UI continues unresponsive, follow these steps:

- 1) Open Windows File Explorer and type in the following path “C:\ProgramData\Gama\logs”;
- 2) Copy all logs and forward them to your Carlson Software Support point of contact;
- 3) Reboot RTk5 tablet.

### 8.8 Installing Tallysman antenna

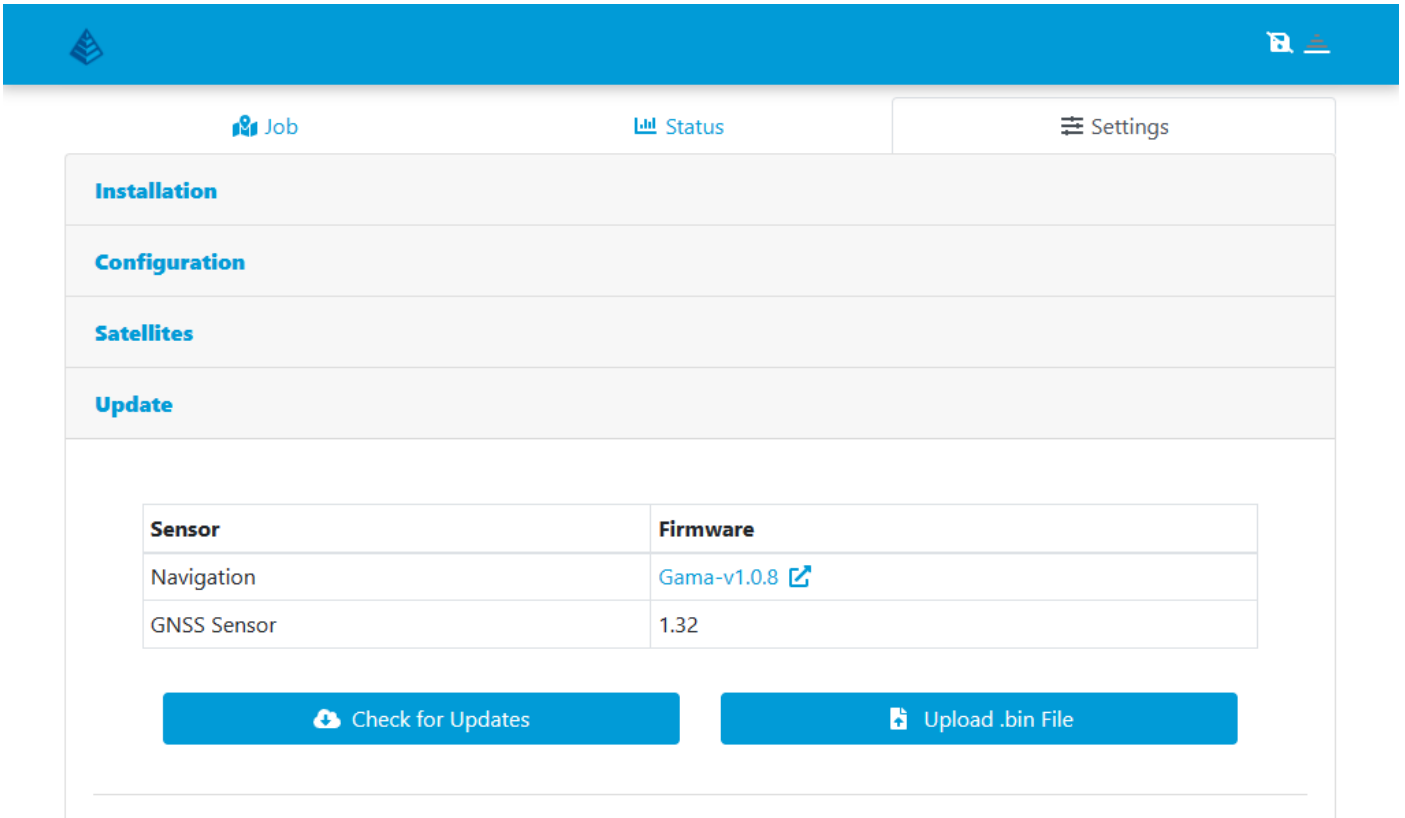
The Tallysman TWI3972XF antenna is screwed directly to the pole. There is no need for bolts, neither rubber, only the ground plate is in between the antenna and the pole. Then, you just pick the right antenna from the SurvPC library (TWI3972XF).




### 8.9 GNSS Sensor Firmware Out-of-Date

To ensure Gama performs optimally, it is required that the GNSS Sensor be operating within a specified range of firmware (FW) versions.

The current FW version of the internal GNSS Sensor is located on the Gama Web UI update section.



The screenshot shows the Gama Web UI interface. At the top, there is a blue navigation bar with a home icon on the left and a search icon on the right. Below the navigation bar, there are three tabs: 'Job', 'Status', and 'Settings'. The 'Settings' tab is selected. Underneath the tabs, there is a vertical list of menu items: 'Installation', 'Configuration', 'Satellites', and 'Update'. The 'Update' menu item is highlighted. Below the menu items, there is a table with two columns: 'Sensor' and 'Firmware'. The table contains two rows: 'Navigation' with firmware 'Gama-v1.0.8' and 'GNSS Sensor' with firmware '1.32'. Below the table, there are two blue buttons: 'Check for Updates' and 'Upload .bin File'.

Sensor	Firmware
Navigation	Gama-v1.0.8 
GNSS Sensor	1.32

At the time of this document, the latest GNSS Sensor firmware is:

**GNSS Sensor: 1.32**

If your displayed version is less than the above, the GNSS Sensor FW can be updated by following the [Updating Gama procedure](#).

