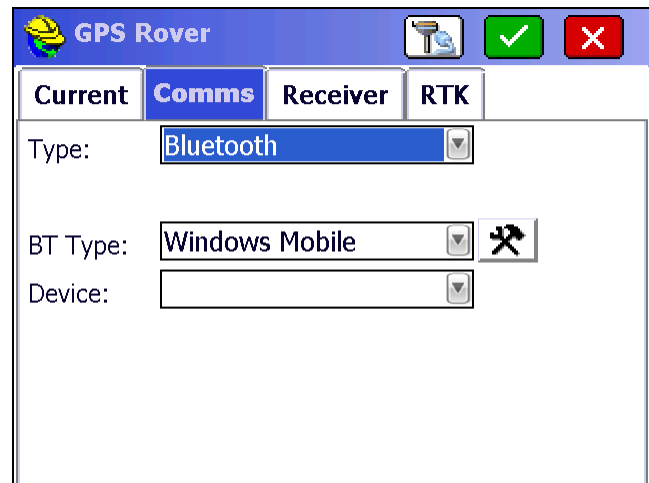


You must, first, establish your Wifi connection, to your device, outside of SurvCE/PC.

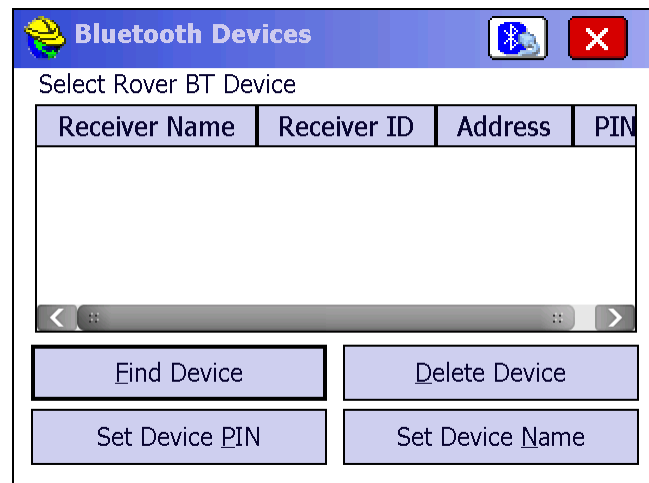
- 1) Launch the SurvCE program.
- 2) Tap on the Equipment tab and select GPS Rover.
- 3) Your manufacturer should be set to *Carlson* and the model should be set to *BRx6* like the screenshot to the right



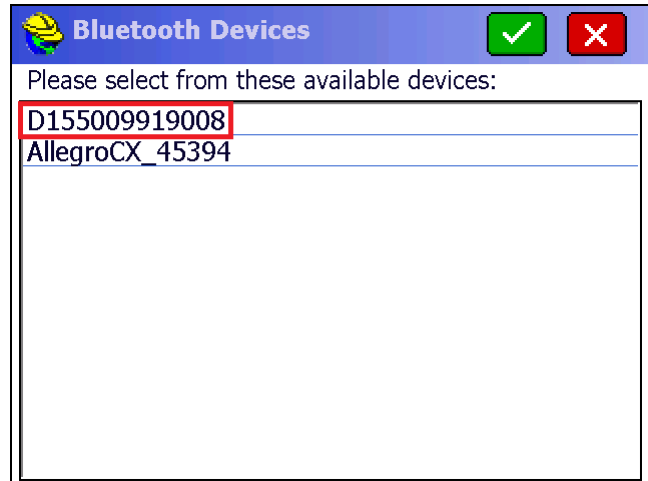
- 4) Tap on the Comms tab to establish the connection to the receiver.
- 5) Set it to Type: *Bluetooth* and BT Type: *Windows Mobile*.
- 6) Then - tap the Tools icon to configure your Bluetooth.



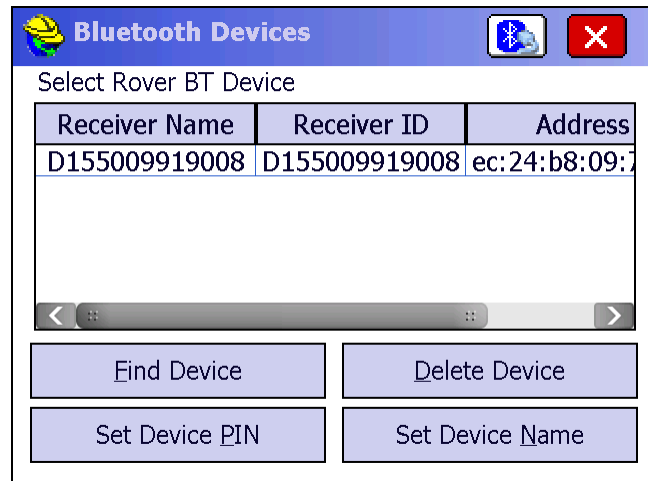
- 7) Tap **Find Device** to search for available Bluetooth devices.



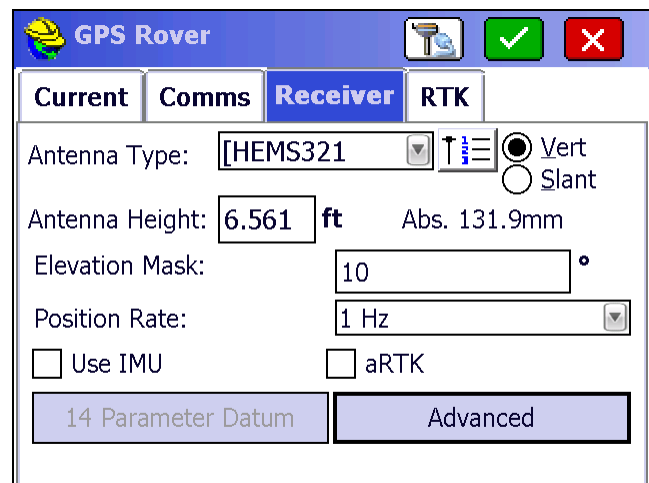
8) Tap to select your receiver's hardware serial number. Then tap the green checkmark.



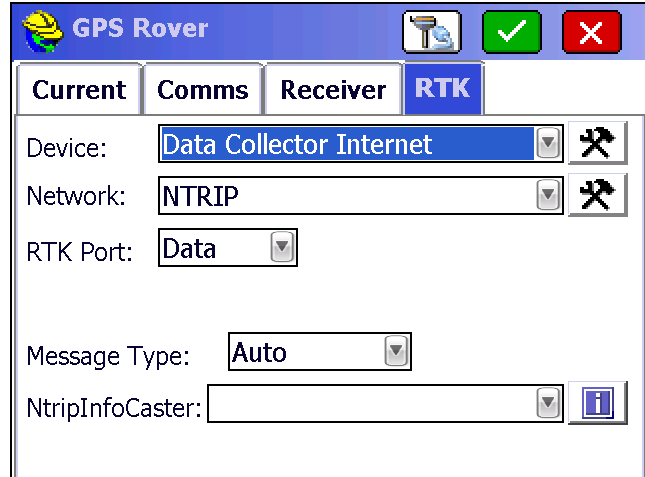
9) Now, highlight the receiver and tap on the Bluetooth icon in the top right to connect to the receiver.



10) Enter your *Vertical* rod measurement in the Receiver tab such as **6.5617** if you are using a fixed height, 2 meter, pole

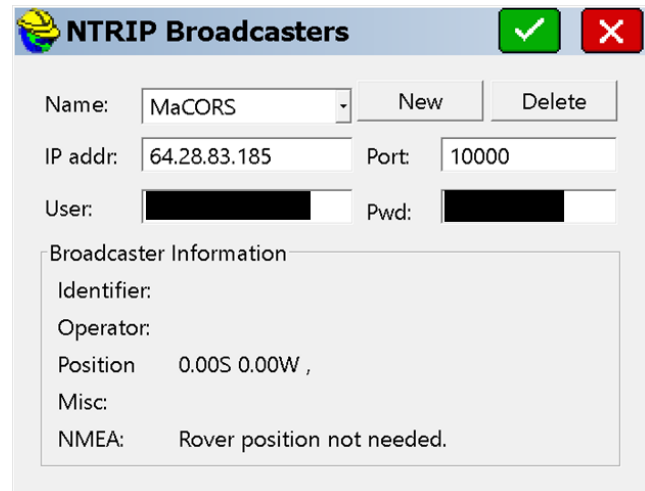


- 11) In the RTK tab, set it to the values below
Device: *Data Collector Internet*
Network: *NTRIP*
RTK Port: *Data*



- 12) Then, tap on the Tools icon, beside NTRIP, to enter your network information.

- 13) Tap the “New” button at the top then type in a nickname for your network connection.



- 14) Enter the IP Address and Port number provided to you by your Network Base provider.

- 15) Enter your User Name and Password, which has been set up with the Network Base provider.

- 16) Tap the green checkmark to download the available Base Mount Points

- 17) Select the *VRS_RTCM3*, *Max_RTCM* or the *RTCM3_Near* option from the list, or check with your statewide network to see which base mountpoint they recommend. Then, tap the Green Check

- 18) If your outdoors with a clear view of the sky you can tap the Green Check to save these new settings and initialize your GPS so it can connect to the Reference Network.

To check the status of your receiver, you can tap the "Monitor Skyplot" button to see if the Latency shows 2.0 or less. After standing in the open for a few minutes, the Quality will change from Autonomous to Float. Then, from Float to Fixed.